The Connected Components of the Projective Line over a Ring

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September 12, 2000

Abstract

The main result of the present paper is that the projective line over a ring R is connected with respect to the relation "distant" if, and only if, R is a GE_2 -ring.

Mathematics Subject Classification (2000): 51C05, 20H25.

1 Introduction

One of the basic notions for the projective line $\mathbb{P}(R)$ over a ring R is the relation distant (\triangle) on the point set. Non-distant points are also called parallel. This terminology goes back to the projective line over the real dual numbers, where parallel points represent parallel spears of the Euclidean plane [4, 2.4].

We say that $\mathbb{P}(R)$ is *connected* (with respect to \triangle) if the following holds: For any two points p and q there is a finite sequence of points starting at p and ending at q such that each point other than p is distant from its predecessor. Otherwise $\mathbb{P}(R)$ is said to be *disconnected*. For each *connected component* a *distance function* and a *diameter* (with respect to \triangle) can be defined in a natural way.

One aim of the present paper is to characterize those rings R for which $\mathbb{P}(R)$ is connected. Here we use certain subgroups of the group $\mathrm{GL}_2(R)$ of invertible 2×2 -matrices over R, namely its elementary subgroup $\mathrm{E}_2(R)$ and the subgroup $\mathrm{GE}_2(R)$ generated by $\mathrm{E}_2(R)$ and the set of all invertible diagonal matrices. It turns out that $\mathbb{P}(R)$ is connected exactly if R is a GE_2 -ring, i.e., if $\mathrm{GE}_2(R) = \mathrm{GL}_2(R)$.

Next we turn to the diameter of connected components. We show that all connected components of $\mathbb{P}(R)$ share a common diameter.

It is well known that $\mathbb{P}(R)$ is connected with diameter ≤ 2 if R is a ring of stable rank 2. We give explicit examples of rings R such that $\mathbb{P}(R)$ has one of the following properties: $\mathbb{P}(R)$ is connected with diameter $\mathfrak{D}(R)$ is connected with diameter $\mathfrak{D}(R)$ is disconnected with diameter $\mathfrak{D}(R)$. In particular, we show that there are *chain geometries* over disconnected projective lines.

^{*}Supported by a Lise Meitner Research Fellowship of the Austrian Science Fund (FWF), project M574-MAT.

2 Preliminaries

Throughout this paper we shall only consider associative rings with a unit element 1, which is inherited by subrings and acts unitally on modules. The trivial case 1 = 0 is not excluded. The group of invertible elements of a ring R will be denoted by R^* .

Firstly, we turn to the projective line over a ring: Consider the free left R-module R^2 . Its automorphism group is the group $GL_2(R)$ of invertible 2×2 -matrices with entries in R. A pair $(a,b) \in R^2$ is called *admissible*, if there exists a matrix in $GL_2(R)$ with (a,b) being its first row. Following [14, 785], the *projective line over* R is the orbit of the free cyclic submodule R(1,0) under the action of $GL_2(R)$. So

$$\mathbb{P}(R) := R(1,0)^{\mathrm{GL}_2(R)}$$

or, in other words, $\mathbb{P}(R)$ is the set of all $p \leq R^2$ such that p = R(a, b) for an admissible pair $(a, b) \in R^2$. As has been pointed out in [8, Proposition 2.1], in certain cases $R(x, y) \in \mathbb{P}(R)$ does not imply the admissibility of $(x, y) \in R^2$. However, throughout this paper we adopt the convention that points are represented by admissible pairs only. Two such pairs represent the same point exactly if they are left-proportional by a unit in R.

The point set $\mathbb{P}(R)$ is endowed with the symmetric relation distant (\triangle) defined by

$$\Delta := (R(1,0), R(0,1))^{GL_2(R)}. \tag{1}$$

Letting p = R(a, b) and q = R(c, d) gives then

$$p \triangle q \iff \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \mathrm{GL}_2(R).$$

In addition, \triangle is anti-reflexive exactly if $1 \neq 0$.

The vertices of the distant graph on $\mathbb{P}(R)$ are the points of $\mathbb{P}(R)$, the edges of this graph are the unordered pairs of distant points. Therefore basic graph-theoretical concepts are at hand: $\mathbb{P}(R)$ can be decomposed into connected components (maximal connected subsets), for each connected component there is a distance function (dist(p,q)) is the minimal number of edges needed to go from vertex p to vertex q), and each connected component has a diameter (the supremum of all distances between its points).

Secondly, we recall that the set of all elementary matrices

$$B_{12}(t) := \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix} \text{ and } B_{21}(t) := \begin{pmatrix} 1 & 0 \\ t & 1 \end{pmatrix} \text{ with } t \in R$$
 (2)

generates the elementary subgroup $E_2(R)$ of $GL_2(R)$. The group $E_2(R)$ is also generated by the set of all matrices

$$E(t) := \begin{pmatrix} t & 1 \\ -1 & 0 \end{pmatrix} = B_{12}(1) \cdot B_{21}(-1) \cdot B_{12}(1) \cdot B_{21}(t) \text{ with } t \in \mathbb{R},$$
 (3)

since $B_{12}(t) = E(-t) \cdot E(0)^{-1}$ and $B_{21}(t) = E(0)^{-1} \cdot E(t)$. Further, $E(t)^{-1} = E(0) \cdot E(-t) \cdot E(0)$ implies that all finite products of matrices E(t) already comprise the group $E_2(R)$.

The subgroup of $GL_2(R)$ which is generated by $E_2(R)$ and the set of all invertible diagonal matrices is denoted by $GE_2(R)$. By definition, a GE_2 -ring is characterized by $GL_2(R) = GE_2(R)$; see, among others, [10, 5] or [18, 114].

3 Connected Components

We aim at a description of the connected components of the projective line $\mathbb{P}(R)$ over a ring R. The following lemma, although more or less trivial, will turn out useful:

Lemma 3.1 Let $X' \in GL_2(R)$ and suppose that the 2×2 -matrix X over R has the same first row as X'. Then X is invertible if, and only if, there is a matrix

$$M = \begin{pmatrix} 1 & 0 \\ s & u \end{pmatrix} \in GE_2(R) \tag{4}$$

such that X = MX'.

Proof: Given X' and X then $XX'^{-1} = \begin{pmatrix} 1 & 0 \\ s & u \end{pmatrix} =: M$ for some $s, u \in R$. Further, X = MX' is invertible exactly if $u \in R^*$. This in turn is equivalent to (4). \square

Here is our main result, where we use the generating matrices of $E_2(R)$ introduced in (3).

Theorem 3.2 Denote by C_{∞} the connected component of the point R(1,0) in the projective line $\mathbb{P}(R)$ over a ring R. Then the following holds:

- (a) The group $GL_2(R)$ acts transitively on the set of connected components of $\mathbb{P}(R)$.
- (b) Let $t_1, t_2, \ldots, t_n \in R$, n > 0, and put

$$(x,y) := (1,0) \cdot E(t_n) \cdot E(t_{n-1}) \cdots E(t_1).$$
 (5)

Then $R(x,y) \in C_{\infty}$ and, conversely, each point $r \in C_{\infty}$ can be written in this way.

- (c) The stabilizer of C_{∞} in $GL_2(R)$ is the group $GE_2(R)$.
- (d) The projective line $\mathbb{P}(R)$ is connected if, and only if, R is a GE₂-ring.

Proof: (a) This is immediate from the fact that the group $GL_2(R)$ acts transitively on the point set $\mathbb{P}(R)$ and preserves the relation \triangle .

(b) Every matrix $E(t_i)$ appearing in (5) maps C_{∞} onto C_{∞} , since $R(0,1) \in C_{\infty}$ goes over to $R(1,0) \in C_{\infty}$. Therefore $R(x,y) \in C_{\infty}$.

On the other hand let $r \in C_{\infty}$. Then there exists a sequence of points $p_i = R(a_i, b_i) \in \mathbb{P}(R)$, $i \in \{0, 1, ..., n\}$, such that

$$R(1,0) = p_0 \triangle p_1 \triangle \dots \triangle p_n = r. \tag{6}$$

Now the arbitrarily chosen admissible pairs (a_i, b_i) are "normalized" recursively as follows: First define $(x_{-1}, y_{-1}) := (0, -1)$ and $(x_0, y_0) := (1, 0)$. So $p_0 = R(x_0, y_0)$. Next assume that we already are given admissible pairs (x_j, y_j) with $p_j = R(x_j, y_j)$ for all $j \in \{0, 1, \ldots, i-1\}$, $1 \le i \le n$. From Lemma 3.1, there are $s_i \in R$ and $u_i \in R^*$ such that

$$\begin{pmatrix} x_{i-1} & y_{i-1} \\ a_i & b_i \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ s_i & u_i \end{pmatrix} \begin{pmatrix} x_{i-1} & y_{i-1} \\ -x_{i-2} & -y_{i-2} \end{pmatrix}.$$
 (7)

By putting $x_i := u_i^{-1} a_i$, $y_i := u_i^{-1} b_i$, and $t_i := u_i^{-1} s_i$ we get

$$\begin{pmatrix} x_i & y_i \\ -x_{i-1} & -y_{i-1} \end{pmatrix} = E(t_i) \cdot \begin{pmatrix} x_{i-1} & y_{i-1} \\ -x_{i-2} & -y_{i-2} \end{pmatrix}$$
(8)

and $p_i = R(x_i, y_i)$. Therefore, finally, (x_n, y_n) is the first row of the matrix

$$G' := E(t_n) \cdot E(t_{n-1}) \cdots E(t_1) \in \mathcal{E}_2(R), \tag{9}$$

and $r = R(x_n, y_n)$.

(c) As has been noticed at the end of Section 2, the set of all matrices (3) generates $E_2(R)$. This together with (b) implies that $E_2(R)$ stabilizes C_{∞} . Further, R(1,0) remains fixed under each invertible diagonal matrix. Therefore $GE_2(R)$ is contained in the stabilizer of C_{∞} .

Conversely, suppose that $G \in GL_2(R)$ stabilizes C_{∞} . Then the first row of G, say (a, b), determines a point of C_{∞} . By (5) and (9), there is a matrix $G' \in E_2(R)$ and a unit $u \in R^*$ such that $(a, b) = (1, 0) \cdot (uG')$. Now Lemma 3.1 can be applied to G and $uG' \in GE_2(R)$ in order to establish that $G \in GE_2(R)$.

(d) This follows from (a) and (c). \Box

From Theorem 3.2 and (9), the connected component of $R(1,0) \in \mathbb{P}(R)$ is given by all pairs of $(1,0) \cdot E_2(R)$ or, equivalently, by all pairs of $(1,0) \cdot GE_2(R)$. Each product (5) gives rise to a sequence

$$(x_i, y_i) = (1, 0) \cdot E(t_i) \cdot E(t_{i-1}) \cdots E(t_1), \ i \in \{0, 1, \dots, n\},$$
 (10)

which in turn defines a sequence $p_i := R(x_i, y_i)$ of points with $p_0 = R(1, 0)$. By putting $p_n =: r$ and by reversing the arguments in the proof of (b), it follows that (6) is true. So, if the diameter of C_{∞} is finite, say $m \geq 0$, then in order to reach all points of C_{∞} it is sufficient that n ranges from 0 to m in formula (5).

By the action of $GL_2(R)$, the connected component C_p of any point $p \in \mathbb{P}(R)$ is $GL_2(R)$ equivalent to the connected component C_{∞} of R(1,0) and the stabilizer of C_p in $GL_2(R)$ is conjugate to $GE_2(R)$. Observe that in general $GE_2(R)$ is not normal in $GL_2(R)$. Cf.
the example in 5.7 (c). All connected components are isomorphic subgraphs of the distant graph.

4 Generalized Chain Geometries

If $K \subset R$ is a (not necessarily commutative) subfield, then the K-sublines of $\mathbb{P}(R)$ give rise to a generalized chain geometry $\Sigma(K,R)$; see [7]. In contrast to an ordinary chain geometry (cf. [14]) it is not assumed that K is in the centre of R. Any three mutually distant points are on at least one K-chain. Two distinct points are distant exactly if they are on a common K-chain. Therefore each K-chain is contained in a unique connected component. Each connected component C together with the set of K-chains entirely contained in it defines an incidence structure $\Sigma(C)$. It is straightforward to show that the automorphism group of

the incidence structure $\Sigma(K, R)$ is isomorphic to the wreath product of Aut $\Sigma(C)$ with the symmetric group on the set of all connected components of $\mathbb{P}(R)$.

If $\Sigma(K,R)$ is a chain geometry then the connected components are exactly the maximal connected subspaces of $\Sigma(K,R)$ [14, 793, 821]. Cf. also [15] and [16].

An R-semilinear bijection of R^2 induces an automorphism of $\Sigma(K,R)$ if, and only if, the accompanying automorphism of R takes K to $u^{-1}Ku$ for some $u \in R^*$. On the other hand, if $\mathbb{P}(R)$ is disconnected then we cannot expect all automorphisms of $\Sigma(K,R)$ to be semilinearly induced. More precisely, we have the following:

Theorem 4.1 Let $\Sigma(K,R)$ be a disconnected generalized chain geometry, i.e., the projective line $\mathbb{P}(R)$ over R is disconnected. Then $\Sigma(K,R)$ admits automorphisms that cannot be induced by any semilinear bijection of R^2 .

Proof: (a) Suppose that two semilinearly induced bijections γ_1, γ_2 of $\mathbb{P}(R)$ coincide on all points of one connected component C of $\mathbb{P}(R)$. We claim that $\gamma_1 = \gamma_2$. For a proof choose two distant points R(a,b) and R(c,d) in C. Also, write α for that projectivity which is given by the matrix $\binom{a}{c} \binom{b}{d}$. Then $\beta := \alpha \gamma_1 \gamma_2^{-1} \alpha^{-1}$ is a semilinearly induced bijection of $\mathbb{P}(R)$ fixing the connected component C_{∞} of R(1,0) pointwise. Hence R(1,0), R(0,1), and R(1,1) are invariant under β , and we get

$$R(x,y)^{\beta} = R(x^{\zeta}u, y^{\zeta}u)$$
 for all $(x,y) \in \mathbb{R}^2$

with $\zeta \in \text{Aut}(R)$ and $u \in R^*$, say. For all $x \in R$ the point R(x, 1) is distant from R(1, 0); so it remains fixed under β . Therefore $x = u^{-1}x^{\zeta}u$ or, equivalently, $x^{\zeta}u = ux$ for all $x \in R$. Finally, $R(x, y)^{\beta} = R(ux, uy) = R(x, y)$ for all $(x, y) \in R^2$, whence $\gamma_1 = \gamma_2$.

(b) Let γ be a non-identical projectivity of $\mathbb{P}(R)$ given by a matrix $G \in GE_2(R)$, for example, $G = B_{12}(1)$. From Theorem 3.2, the connected component C_{∞} of R(1,0) is invariant under γ . Then

$$\delta: \mathbb{P}(R) \to \mathbb{P}(R): \left\{ \begin{array}{l} p \mapsto p^{\gamma} & \text{for all } p \in C_{\infty} \\ p \mapsto p & \text{for all } p \in \mathbb{P}(R) \setminus C_{\infty} \end{array} \right.$$
 (11)

is an automorphism of $\Sigma(K, R)$. The projectivity γ and the identity on $\mathbb{P}(R)$ are different and both are linearly induced. The mapping δ coincides with γ on C_{∞} and with the identity on every other connected component. There are at least two distinct connected components of $\mathbb{P}(R)$. Hence it follows from (a) that δ cannot be semilinearly induced. \square

If a cross-ratio in $\mathbb{P}(R)$ is defined according to [14, 1.3.5] then four points with cross-ratio are necessarily in a common connected component. Therefore, the automorphism δ defined in (11) preserves all cross-ratios. However, cross-ratios are not invariant under δ if one adopts the definition in [4, 90] or [14, 7.1] which works for commutative rings only. This is due to the fact that here four points with cross-ratio can be in two distinct connected components. We shall give examples of disconnected (generalized) chain geometries in the next section.

5 Examples

There is a widespread literature on (non-)GE₂-rings. We refer to [1], [9], [10], [11], [12], [13], and [18]. We are particularly interested in rings containing a field and the corresponding generalized chain geometries.

Remark 5.1 Let R be a ring. Then each admissible pair $(x, y) \in R^2$ is unimodular, i.e., there exist $x', y' \in R$ with xx' + yy' = 1. We remark that

$$(x,y) \in \mathbb{R}^2 \text{ unimodular} \Rightarrow (x,y) \text{ admissible}$$
 (12)

is satisfied, in particular, for all *commutative* rings, since xx' + yy' = 1 can be interpreted as the determinant of an invertible matrix with first row (x, y). Also, all rings of *stable rank* 2 [19, 293] satisfy (12); cf. [19, 2.11]. For example, local rings, matrix rings over fields, and finite-dimensional algebras over commutative fields are of stable rank 2. See [13, 4.1B], [19, $\S 2$], [20], and the references given there.

The following example shows that (12) does not hold for all rings: Let R := K[X, Y] be the polynomial ring over a proper skew field K in independent central indeterminates X and Y. There are $a, b \in K$ with $c := ab - ba \neq 0$. From

$$(X+a)(Y+b)c^{-1} - (Y+b)(X+a)c^{-1} = 1,$$

the pair $(X+a, -(Y+b)) \in \mathbb{R}^2$ is unimodular. However, this pair is not admissible: Assume to the contrary that (X+a, -(Y+b)) is the first row of a matrix $M \in GL_2(\mathbb{R})$ and suppose that the second column of M^{-1} is the transpose of $(v_0, w_0) \in \mathbb{R}^2$. Then

$$P := \{(v, w) \in \mathbb{R}^2 \mid (X + a)v - (Y + b)w = 0\} = (v_0, w_0)R.$$

On the other hand, by [17, Proposition 1], the right R-module P cannot be generated by a single element, which is a contradiction.

Examples 5.2 (a) If R is a ring of stable rank 2 then $\mathbb{P}(R)$ is connected and its diameter is ≤ 2 [14, Proposition 1.4.2]. In particular, the diameter is 1 exactly if R is a field and it is 0 exactly if $R = \{0\}$.

As has been pointed out in [2, (2.1)], the points of the projective line over a ring R of stable rank 2 are exactly the submodules $R(t_2t_1+1,t_2)$ of R^2 with $t_1,t_2 \in R$. Clearly, this is just a particular case of our more general result in Theorem 3.2 (b).

Conversely, if an arbitrary ring R satisfies (12) and $\mathbb{P}(R)$ is connected with diameter ≤ 2 , then R is a ring of stable rank 2 [14, Proposition 1.1.3].

(b) The projective line over a (not necessarily commutative) Euclidean ring R is connected, since every Euclidean ring is a GE₂-ring [13, Theorem 1.2.10].

Our next examples are given in the following theorem:

Theorem 5.3 Let U be an infinite-dimensional vector space over a field K and put $R := \operatorname{End}_K(U)$. Then the projective line $\mathbb{P}(R)$ over R is connected and has diameter 3.

Proof: We put $V := U \times U$ and denote by \mathcal{G} those subspaces W of V that are isomorphic to V/W. By [5, 2.4], the mapping

$$\Phi: \mathbb{P}(R) \to \mathcal{G}: R(\alpha, \beta) \mapsto \{(u^{\alpha}, u^{\beta}) \mid u \in U\}$$
(13)

is bijective and two points of $\mathbb{P}(R)$ are distant exactly if their Φ -images are complementary. By an abuse of notation, we shall write $\operatorname{dist}(W_1, W_2) = n$, whenever W_1, W_2 are Φ -images of points at distance n, and $W_1 \triangle W_2$ to denote complementary elements of \mathcal{G} . As V is infinite-dimensional, $2 \dim W = \dim V = \dim W$ for all $W \in \mathcal{G}$.

We are going to verify the theorem in terms of \mathcal{G} : So let $W_1, W_2 \in \mathcal{G}$. Put $Y_{12} := W_1 \cap W_2$ and choose $Y_{23} \leq W_2$ such that $W_2 = Y_{12} \oplus Y_{23}$. Then $W_1 \cap Y_{23} = \{0\}$ so that there is a $W_3 \in \mathcal{G}$ through Y_{23} with $W_1 \triangle W_3$. By the law of modularity,

$$W_2 \cap W_3 = (Y_{23} + Y_{12}) \cap W_3 = Y_{23} + (Y_{12} \cap W_3) = Y_{23}.$$

Finally, choose $Y_{14} \leq W_1$ with $W_1 = Y_{12} \oplus Y_{14}$ and $Y_{34} \leq W_3$ with $W_3 = Y_{23} \oplus Y_{34}$. Hence we arrive at the decomposition

$$V = Y_{14} \oplus Y_{12} \oplus Y_{23} \oplus Y_{34}. \tag{14}$$

As $W_2 \in \mathcal{G}$, so is also $W_4 := Y_{14} \oplus Y_{34}$. Now there are two possibilities:

Case 1: There exists a linear bijection $\sigma: Y_{14} \to Y_{23}$. We define $Y := \{v + v^{\sigma} \mid v \in Y_{14}\}$. Then Y_{14}, Y_{23} , and Y are easily seen to be mutually complementary subspaces of $Y_{14} \oplus Y_{23}$. Therefore, from (14),

$$V = Y_{14} \oplus Y_{12} \oplus Y \oplus Y_{34} = Y \oplus Y_{12} \oplus Y_{23} \oplus Y_{34}, \tag{15}$$

i.e., $W_1 \triangle (Y \oplus Y_{34}) \triangle W_2$. So $\operatorname{dist}(W_1, W_2) \leq 2$.

Case 2: Y_{14} and Y_{23} are not isomorphic. Then dim $Y_{12} = \dim W_1$, since otherwise dim $Y_{12} < \dim W_1 = \dim W_2$ together with well-known rules for the addition of infinite cardinal numbers would imply

$$\dim W_1 = \max \{\dim Y_{12}, \dim Y_{14}\} = \dim Y_{14},$$

 $\dim W_2 = \max \{\dim Y_{12}, \dim Y_{23}\} = \dim Y_{23},$

a contradiction to dim $Y_{14} \neq \dim Y_{23}$.

Likewise, it follows that dim $Y_{34} = \dim W_3$. But this means that Y_{12} and Y_{34} are isomorphic, whence the proof in case 1 can be modified accordingly to obtain a $Y \leq Y_{12} \oplus Y_{34}$ such that $W_1 \triangle W_3 \triangle (Y \oplus Y_{14}) \triangle W_2$. So now dist $(W_1, W_2) \leq 3$.

It remains to establish that in \mathcal{G} there are elements with distance 3: Choose any subspace $W_1 \in \mathcal{G}$ and a subspace $W_2 \leq W_1$ such that W_1/W_2 is 1-dimensional. With the previously introduced notations we get $Y_{12} = W_2$, dim $Y_{14} = 1$, $Y_{23} = \{0\}$, $Y_{34} = W_3 \in \mathcal{G}$, and $W_4 = Y_{14} \oplus W_3$. As before, $V = W_2 \oplus W_4$ and from dim $W_2 = 1 + \dim W_2 = \dim W_1 = \dim W_3 = 1 + \dim W_3 = \dim W_4$ we obtain $W_2, W_4 \in \mathcal{G}$. By construction, dist $(W_1, W_2) \neq 0, 1$. Also, this distance cannot be 2, since $W \triangle W_1$ implies $W + W_2 \neq V$ for all $W \in \mathcal{G}$.

This completes the proof. \Box

If K is a proper skew field, then K can be embedded in $\operatorname{End}_K(U)$ in several ways [6, 17]; each embedding gives rise to a connected generalized chain geometry. (In [6] this is just called a "chain geometry".) If K is commutative, then $\operatorname{End}_K(U)$ is a K-algebra and $x \mapsto x \operatorname{id}_U$ is a distinguished embedding of K into the centre of $\operatorname{End}_K(U)$. In this way an ordinary connected chain geometry arises; cf. [14, 4.5. Example (4)].

Our next goal is to show the existence of chain geometries with connected components of infinite diameter.

Remark 5.4 If R is an arbitrary ring then each matrix $A \in GE_2(R)$ can be expressed in standard form

$$A = \operatorname{diag}(u, v) \cdot E(t_n) \cdot E(t_{n-1}) \cdots E(t_1), \tag{16}$$

where $u, v \in R^*$, $t_1, t_n \in R$, $t_2, t_3, \ldots, t_{n-1} \in R \setminus (R^* \cup \{0\})$, and $t_1, t_2 \neq 0$ in case n = 2 [10, Theorem (2.2)]. Since $E(0)^2 = \operatorname{diag}(-1, -1)$, each matrix $A \in \operatorname{GE}_2(R)$ can also be written in the form (16) subject to the slightly modified conditions $u, v \in R^*$, $t_1, t_n \in R$, $t_2, t_3, \ldots, t_{n-1} \in R \setminus (R^* \cup \{0\})$, and $n \geq 1$. We call this a modified standard form of A.

Suppose that there is a unique standard form for $GE_2(R)$. For all non-diagonal matrices in $GE_2(R)$ the unique representation in standard form is at the same time the unique representation in modified standard form. Any diagonal matrix $A \in GE_2(R)$ is already expressed in standard form, but its unique modified standard form reads $A = -A \cdot E(0)^2$. Therefore there is also a unique modified standard form for $GE_2(R)$.

By reversing these arguments it follows that the existence of a unique modified standard form for $GE_2(R)$ is equivalent to the existence of a unique standard form for $GE_2(R)$.

Theorem 5.5 Let R be a ring with a unique standard form for $GE_2(R)$ and suppose that R is not a field. Then every connected component of the projective line $\mathbb{P}(R)$ over R has infinite diameter.

Proof: Since R is not a field, there exists an element $t \in R \setminus (R^* \cup \{0\})$. We put

$$q_m := R(c_m, d_m) \text{ where } (c_m, d_m) := (1, 0) \cdot E(t)^m \text{ for all } m \in \{0, 1, \ldots\}.$$
 (17)

Next fix one $m \ge 1$, and put $n-1 := \operatorname{dist}(q_0, q_{m-1}) \ge 0$. Hence there exists a sequence

$$p_0 \triangle p_1 \triangle \dots \triangle p_{n-1} \triangle p_n \tag{18}$$

such that $p_0 = q_0$, $p_{n-1} = q_{m-1}$, and $p_n = q_m$. Now we proceed as in the proof of Theorem 3.2 (b): First let $p_i = R(a_i, b_i)$ and put $(x_{-1}, y_{-1}) := (0, -1)$, $(x_0, y_0) := (1, 0)$. Then pairs $(x_i, y_i) \in R^2$ and matrices $E(t_i) \in E_2(R)$ are defined in such a way that $p_i = R(x_i, y_i)$ and that (8) holds for $i \in \{1, 2, ..., n\}$. It is immediate from (8) that a point p_i , $i \geq 2$, is distant from p_{i-2} exactly if $t_i \in R^*$. Also, $p_i = p_{i-2}$ holds if, and only if, $t_i = 0$. We infer from (8) and dist $(p_i, p_j) = |i - j|$ for all $i, j \in \{0, 1, ..., n-1\}$ that

$$\begin{pmatrix} x_n & y_n \\ -x_{n-1} & -y_{n-1} \end{pmatrix} = E(t_n) \cdot E(t_{n-1}) \cdots E(t_1), \tag{19}$$

where $t_i \in R \setminus (R^* \cup \{0\})$ for all $i \in \{2, 3, ..., n-1\}$. On the other hand, by (17) and $(c_{m-1}, d_{m-1}) = (0, -1) \cdot E(t)^m$, there are $v, v' \in R^*$ with

$$\begin{pmatrix} x_n & y_n \\ -x_{n-1} & -y_{n-1} \end{pmatrix} = \operatorname{diag}(v, v') \cdot E(t)^m. \tag{20}$$

From Remark 5.4, the modified standard forms (19) and (20) are identical. Therefore, n = m, $\operatorname{dist}(q_0, q_{m-1}) = m - 1$, and the diameter of the connected component of q_0 is infinite. By Theorem 3.2 (a), all connected components of $\mathbb{P}(R)$ have infinite diameter. \square

Remark 5.6 Let R be a ring such that $R^* \cup \{0\}$ is a field, say K, and suppose that we have a degree function, i.e. a function deg : $R \to \{-\infty\} \cup \{0, 1, ...\}$ satisfying

$$\deg a = -\infty \quad \text{if, and only if, } a = 0,$$

$$\deg a = 0 \quad \text{if, and only if, } a \in R^*,$$

$$\deg(a+b) \leq \max\{\deg a, \deg b\},$$

$$\deg(ab) = \deg(a) + \deg(b),$$

for all $a, b \in R$. Then, following [10, 21], R is called a K-ring with a degree function. If R is a K-ring with a degree function, then there is a unique standard form for $GE_2(R)$ [10, Theorem (7.1)].

Examples 5.7 (a) Let R be a K-ring with a degree-function such that $R \neq K$. From Remark 5.6 and Theorem 5.5, all connected components of the projective line $\mathbb{P}(R)$ have infinite diameter.

The associated generalized chain geometry $\Sigma(K,R)$ has a lot of strange properties. For example, any two distant points are joined by a unique K-chain. However, we do not enter a detailed discussion here.

- (b) Let K[X] be the polynomial ring over a field K in a central indeterminate X. From (a) and Example 5.2 (b), the projective line $\mathbb{P}(K[X])$ is connected and its diameter is infinite. On the other hand, if K is commutative then K[X] has stable rank 3 [20, 2.9]; see also [3, Chapter V, (3.5)]. So there does not seem to be an immediate connection between stable rank and diameter.
- (c) Let $R := K[X_1, X_2, ..., X_m]$ be the polynomial ring over a field K in m > 1 independent central indeterminates. Then, by an easy induction and by [10, Proposition (7.3)],

$$A_n := \begin{pmatrix} 1 + X_1 X_2 & X_1^2 \\ -X_2^2 & 1 - X_1 X_2 \end{pmatrix}^n = \begin{pmatrix} 1 + n X_1 X_2 & n X_1^2 \\ -n X_2^2 & 1 - n X_1 X_2 \end{pmatrix}$$
(21)

is in $GL_2(R) \setminus GE_2(R)$ for all $n \in \mathbb{Z}$ that are not divisible by the characteristic of K. Also, the inner automorphism of $GL_2(R)$ arising from the matrix A_1 takes $B_{12}(1) \in E_2(R)$ to a matrix that is not even in $GE_2(R)$; see [18, 121–122]. So neither $E_2(R)$ nor $GE_2(R)$ is a normal subgroup of $GL_2(R)$.

We infer that the projective line over R is not connected. Further, it follows from (21) that the number of right cosets of $GE_2(R)$ in $GL_2(R)$ is infinite, if the characteristic of K is zero, and \geq char K otherwise. From Theorem 3.2, this number of right cosets is at the same time the number of connected components in $\mathbb{P}(R)$. Even in case of char K = 2 there are at least three connected components, since the index of $GE_2(R)$ in $GL_2(R)$ cannot be two. From (a), all connected components of $\mathbb{P}(R)$ have infinite diameter.

So, for each commutative field K, we obtain a disconnected chain geometry $\Sigma(K, R)$, whereas for each skew field K a disconnected generalized chain geometry arises.

Acknowledgement. The authors are obliged to the referee for pointing out the paper [17].

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