## A distance space on Cayley's ruled surface

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DIFFERENTIALGEOMETRIE UND GEOMETRISCHE STRUKTUREN

#### Basic notions

Let  $\mathbb{P}_3(K)$  be the 3-dimensional projective space over a commutative field K.

Given a homogeneous polynomial  $g(\mathbf{X}) \in K[\mathbf{X}] = K[X_0, X_1, X_2, X_3]$  then

$$\mathcal{V}(g(\boldsymbol{X})) := \{ K\boldsymbol{p} \in \mathbb{P}_3(K) \mid g(\boldsymbol{p}) = 0 \}$$

denotes the set of K-rational points of the variety given by this form.

We regard  $\omega := \mathcal{V}(X_0)$  as the *plane at infinity*.

## Cayley's ruled cubic surface

The Cayley surface is given by  $F := \mathcal{V}(f(X))$ , where

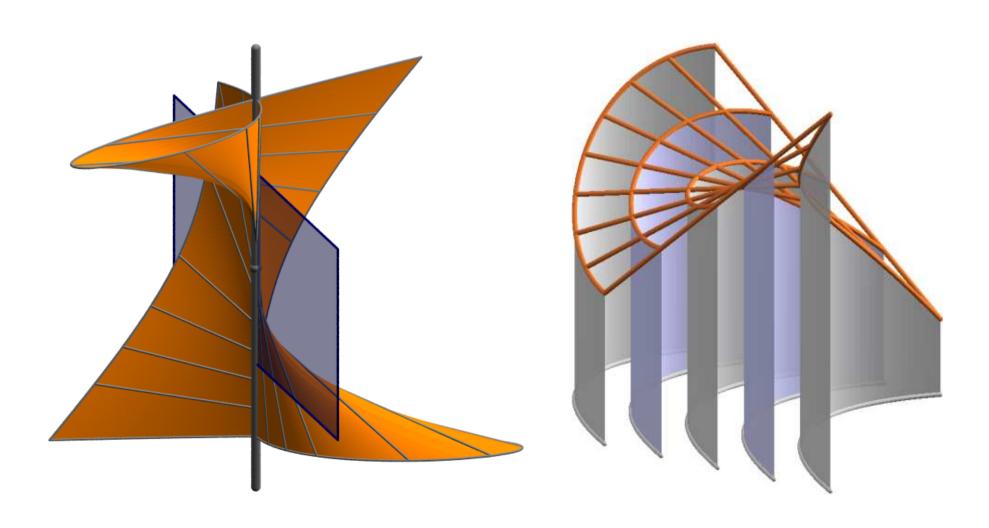
$$f(\mathbf{X}) := X_0 X_1 X_2 - X_1^3 - X_0^2 X_3. \tag{1}$$

The parametrization

$$K^2 \to \mathbb{P}_3(K) : (u_1, u_2) \mapsto K(1, u_1, u_2, u_1 u_2 - u_1^3)^{\mathrm{T}} =: P(u_1, u_2)$$
 (2)

is injective, and its image coincides with  $F \setminus \omega$  (the affine part of F).

# Two pictures



#### Automorphic collineations

The set of all matrices

$$M_{a,b,c} := \begin{pmatrix} 1 & 0 & 0 & 0 \\ a & c & 0 & 0 \\ b & 3ac & c^2 & 0 \\ ab - a^3 & bc & ac^2 & c^3 \end{pmatrix}$$
 (3)

where  $a, b \in K$  and  $c \in K \setminus \{0\}$  is a group, say G(F), under multiplication.

Each matrix in G(F) leaves invariant the cubic form f(X) to within the factor  $c^3$ . Consequently, the group G(F) acts on F as a group of projective collineations.

**Theorem 1.** There are no automorphic projective collineations of the Cayley surface F other than the ones given by (3) if, and only if,  $|K| \geq 4$ .

### A distance function on $F \setminus \omega$

From now on we shall assume  $|K| \ge 4$ .

We define a function

$$\delta: (F \setminus \omega) \times (F \setminus \omega) \to K \cup \{\infty\}$$

as follows. Let  $A = P(u_1, u_2)$  and  $B = P(v_1, v_2)$ , where  $u_1, u_2, v_1, v_2 \in K$ .

- $u_1 = v_1 \Leftrightarrow A, B$  are on a common generator of  $F: \delta(A, B) := \infty$   $(A \parallel B \dots parallel points)$
- $u_1 \neq v_1$ ,  $AB \cap F =: \{A, B, C\}$ ,  $AB \cap \omega := \{I\}$ :

$$\delta(A,B) := \operatorname{CR}(C,B,A,I) = \frac{2u_1^2 - u_2 - u_1v_1 + v_2 - v_1^2}{(u_1 - v_1)^2}$$

### Properties of the distance function

The following properties hold for all  $A, B \in F \setminus \omega$ :

- $\delta(A,A) = \infty$ .
- There exists a point  $C \in F \setminus \omega$  with  $C \neq A$  and  $\delta(A, C) = \infty$ .
- $\delta(A, B) = 1 \delta(B, A)$  (with  $1 \infty := \infty$ ).
- $\delta(A,B) \in \{0,1\} \Leftrightarrow AB$  is a tangent of F.

H. Brauner (1964),  $K = \mathbb{R}$  using differential geometry and Lie groups:

$$\widehat{\delta}(A,B):=\tfrac{3}{2}\left(\tfrac{1}{2}-\delta(A,B)\right)^{-1}\text{, }\widehat{\delta}(A,A)=0\text{, and }\widehat{\delta}(A,B)=-\widehat{\delta}(B,A).$$

#### Circles

Given a point  $A \in F \setminus \omega$  and an element  $\rho \in K \cup \{\infty\}$  we define the *circle with midpoint* A and radius  $\rho$  in the obvious way as

$$\mathcal{C}(A,\rho) := \{ Y \in F \setminus \omega \mid \delta(A,Y) = \rho \}.$$

By the extended circle  $\mathcal{E}(A,\rho)$  we mean the circle  $\mathcal{C}(A,\rho)$  together with its midpoint A.

### A family of curves

For all  $\alpha, \beta, \gamma \in K$  the rationally parameterized curve

$$\mathcal{R}_{\alpha,\beta,\gamma} := \left\{ K(1,t,\alpha+\beta t + (\gamma+1)t^2, \alpha t + \beta t^2 + \gamma t^3)^{\mathrm{T}} \mid t \in K \cup \{\infty\} \right\}$$
 (4)

is lying on F. It is

- a parabola for  $\gamma = 0$ ,
- a planar cubic for  $\gamma = -1$ ,
- a *twisted cubic parabola* (i.e. a twisted cubic having the plane at infinity as an osculating plane) otherwise.

**Remark.**  $F \setminus \omega$  together with the affine traces of the curves (4) is isomorphic to the affine chain geometry on the ring  $K[\varepsilon]$  of dual numbers over K. An isomorphism is given by  $P(u_1, u_2) \mapsto u_1 + \varepsilon u_2$ .

#### Description of extended circles

**Proposition 2.** Suppose that a point  $A = P(a_1, a_2), a_1, a_2 \in K$ , and an element  $\rho \in K \cup \{\infty\}$  are given.

• If  $\rho \in K$  then the extended circle  $\mathcal{E}(A, \rho)$  equals the set of affine points of  $\mathcal{R}_{\alpha,\beta,\gamma}$ , where

$$\alpha := (\rho - 2)a_1^2 + a_2, \ \beta := (1 - 2\rho)a_1, \ \gamma := \rho.$$

• If  $\rho = \infty$  then  $C(A, \rho) = \mathcal{E}(A, \rho)$  is the unique generator of F through A, but without its point at infinity.

**Proposition 3.** Given a curve  $\mathcal{R}_{\alpha,\beta,\gamma}$ , with  $\alpha,\beta,\gamma \in K$ , there are three possibilities.

(a)  $1-2\gamma \neq 0$ :  $\mathcal{R}_{\alpha,\beta,\gamma} \setminus \omega$  coincides with the extended circle  $\mathcal{E}(A,\rho)$ , where

$$A := P\left(\frac{\beta}{1 - 2\gamma}, \alpha - \frac{(\gamma - 2)\beta^2}{(1 - 2\gamma)^2}\right) \text{ and } \rho := \gamma.$$

- (b)  $1 2\gamma = 0 \neq \beta : \mathcal{R}_{\alpha,\beta,\gamma} \setminus \omega \text{ is not an extended circle.}$
- (c)  $1 2\gamma = 0 = \beta : \mathcal{R}_{\alpha,\beta,\gamma} \setminus \omega$  is an extended circle  $\mathcal{E}(A, \frac{1}{2})$  for all points  $A \in \mathcal{R}_{\alpha,\beta,\gamma} \setminus \omega$ .

 $\operatorname{Char} K \neq 2$ : All cases occur.

 $\operatorname{Char} K = 2$ :  $1 - 2\gamma = 1 \neq 0$ . There are no circles with more than one midpoint.

## Transitivity of G(F)

**Theorem 4.** The matrix group G(F) has the following properties:

- (a) G(F) acts on  $F \setminus \omega$  as a group of isometries.
- (b) G(F) acts regularly on the set of antiflags of  $F \setminus \omega$ .
- (c) For each  $d \in K$  the group G(F) acts regularly on the set

$$\Delta_d := \{ (A, B) \in (F \setminus \omega)^2 \mid \delta(A, B) = d \}.$$

(d) Given  $A = P(u_1, u_2) \parallel B = P(u_1, v_2)$  and  $A' = P(u'_1, u'_2) \parallel B' = P(u'_1, v'_2)$ , with  $u_1, u_2, \ldots, v'_2 \in K$ , the number of matrices in G(F) mapping (A, B) to (A', B') equals the number of distinct elements  $c \in K \setminus \{0\}$  such that

$$c^{2}(v_{2}-u_{2})=(v_{2}'-u_{2}').$$

#### All isometries

Following W. Benz an *isometry* of  $F\setminus\omega$  is just a mapping  $\mu:F\setminus\omega\to F\setminus\omega$  such that

$$\delta(A,B) = \delta(\mu(A),\mu(B))$$
 for all  $A,B \in F \setminus \omega$ .

**Theorem 5.** Each isometry  $\mu: F \setminus \omega \to F \setminus \omega$  is induced by a unique matrix in G(F). Consequently,  $\mu$  is bijective and it can be extended in a unique way to a projective collineation of  $\mathbb{P}_3(K)$  fixing the Cayley surface F.