

Isotropic Geometry and Applications in Geometric Computing

K.Yorov, B.Wang, M.Skopenkov, H.Pottmann

khusrav.yorov@kaust.edu.sa

جامعة الملك عبد الله
للعلوم والتقنية
King Abdullah University of
Science and Technology



TECHNISCHE
UNIVERSITÄT
WIEN
Vienna University of Technology

DGS, September 2024, Vienna, Austria

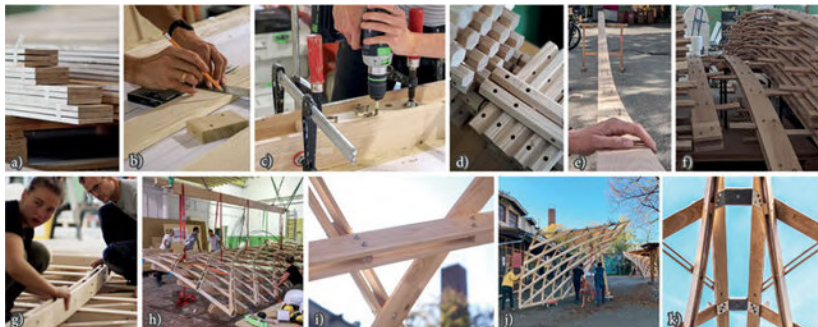


Timber Gridshell 2023 (Schling et al.)



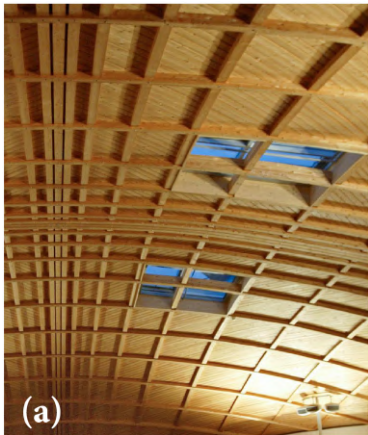


Timber Gridshell 2023 (Schling et al.)





Strips tangential (Natterer et al. 2000)



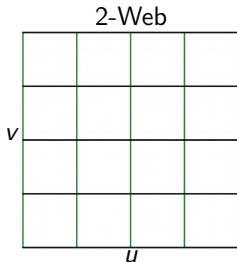
Strips orthogonal (Schling et al. 2022)





Consider a surface S with a parametric representation $s(u, v)$.

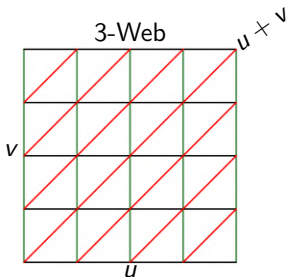
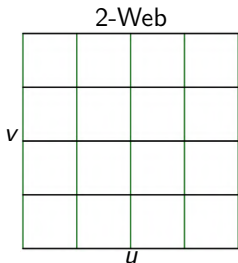
- ▶ The net of isoparameter curves $u = \text{const}$ and $v = \text{const}$ is called a **2-web** on S .





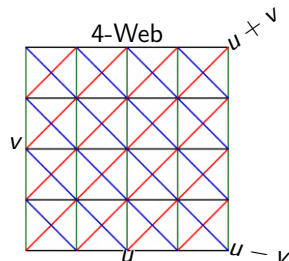
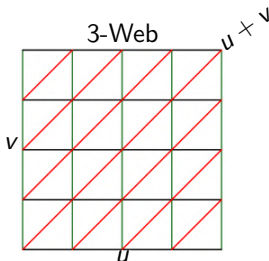
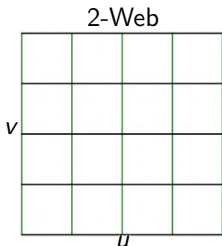
Consider a surface S with a parametric representation $s(u, v)$.

- ▶ The net of isoparameter curves $u = \text{const}$ and $v = \text{const}$ is called a **2-web** on S .
- ▶ The net of isoparameter curves $u = \text{const}$ and $v = \text{const}$ extended by diagonal curves $u + v = \text{const}$ is a **3-web (hexagonal)** on S .
- ▶



Consider a surface S with a parametric representation $s(u, v)$.

- ▶ The net of isoparameter curves $u = \text{const}$ and $v = \text{const}$ is called a **2-web** on S .
- ▶ The net of isoparameter curves $u = \text{const}$ and $v = \text{const}$ extended by diagonal curve $u + v = \text{const}$ is a **(hexagonal) 3-web** on S .
- ▶ The net of isoparameter curves $u = \text{const}$ and $v = \text{const}$ extended by both diagonal curves $u \pm v = \text{const}$ is called a **4-web** on S .





- ▶ **AA:** 2-web formed by 2 families of asymptotic lines on a surface.
AA Web (Schling et al.)





- ▶ **AA:** 2-web formed by 2 families of asymptotic lines on a surface.
- ▶ **GG:** 2-web formed by 2 families of geodesic lines on a surface.

AA Web (Schling et al.)



GG Web (EPF Lausanne)





Definition

A 3-web is called a **GGG web** if each family of curves is geodesic.

Mayrhofer: derives the PDE, but finding an explicit solution is challenging.

Problem: Numerically constructing surfaces with non-constant Gaussian curvature that can be accurately approximated by using the GGG web.

GGG Web (Jorge et al.)



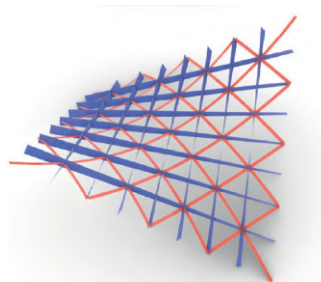
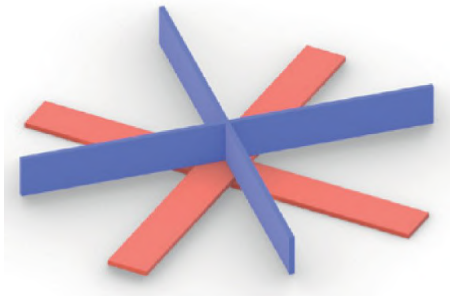


Definition (Schling et al. 2022)

Consider a 4-web on a negatively curved surface such that two families of curves are asymptotic (A), while the other two are geodesics (G). These curves are cyclically organized around each point, following a pattern of A-G-A-G. Such a web is called an **AGAG-web**.

Problem: Find a non-trivial discrete or smooth AGAG-web.

AGAG structure (Schling et al. 2022)





1. Deng, B., Pottmann, H., Wallner, J. (2011).: Optimization of triangle meshes with two geodesic polyline families, and every 4th polyline of the third type is circular and vertical.
2. Schling, E., Wang, H., Hoyer, S., Pottmann, H., (2022).: Workflow for hybrid asymptotic-geodesic webs design.
3. Wang, B., Wang, H., Schling, E., Pottmann, H., (2023).: Designing 3-webs (AAG, AGG, PGG).
4. Pottmann, H., Müller, C., (2023).: Description of all discrete AGAG-webs in isotropic space.

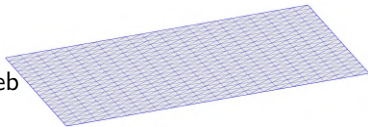


- ▶ By quadratic optimization.
- ▶ Use **isotropic initialization** as the initial shape.
- ▶ During optimization, use a special dot product that gradually transitions from the **isotropic dot product** to the Euclidean one.

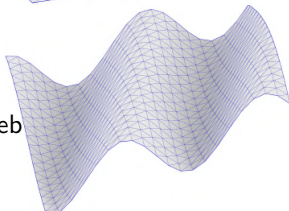


- ▶ An **isotropic geodesic** is a curve on a surface (without vertical tangents) such that the top view is a straight line (simpler than the Euclidean constraint of orthogonal osculating planes).

planar GGG web



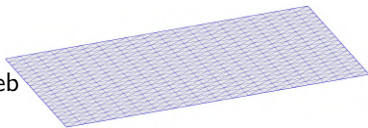
isotropic GGG web



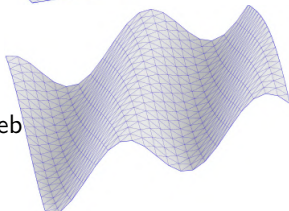


- ▶ An **isotropic geodesic** is a curve on a surface (without vertical tangents) such that the top view is a straight line (simpler than the Euclidean constraint of orthogonal osculating planes).
- ▶ The projection of an isotropic GGG web onto the xy -plane is a 3-web of straight lines. These webs consist of the tangents to an algebraic curve of degree 3, which is dual to a cubic curve [Graf and Sauer, 1924].

planar GGG web



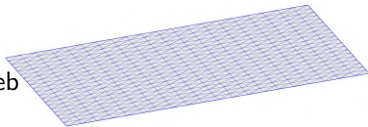
isotropic GGG web



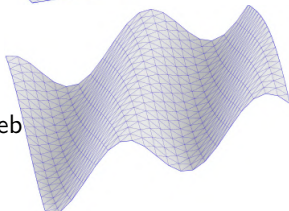


- ▶ An **isotropic geodesic** is a curve on a surface (without vertical tangents) such that the top view is a straight line (simpler than the Euclidean constraint of orthogonal osculating planes).
- ▶ The projection of an isotropic GGG web onto the xy -plane is a 3-web of straight lines. These webs consist of the tangents to an algebraic curve of degree 3, which is dual to a cubic curve [Graf and Sauer, 1924].
- ▶ We can obtain all isotropic GGG webs by projecting a 3-web of straight lines onto a surface.

planar GGG web



isotropic GGG web

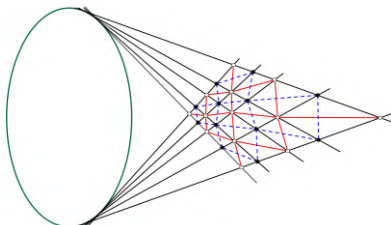




Asymptotic curves are a concept of projective geometry and thus are the same in Euclidean and isotropic geometry.

Algorithm to construct a discrete isotropic AGAG (Müller and Pottmann 2023).

- ▶ Select two one-parameter families of tangent lines to a conic C .
- ▶ Extract a 2-web from the intersection of the tangent lines.
- ▶ Draw the two diagonal nets of the 2-web (two planar Koenigs nets).
- ▶ Apply the construction by Müller and Pottmann to obtain a discrete isotropic AGAG web.





- Inner product of two vectors $p, q \in R^3$ is

$$\langle p, q \rangle = p_1 q_1 + p_2 q_2 + p_3 q_3.$$



- ▶ Inner product of two vectors $p, q \in R^3$ is

$$\langle p, q \rangle = p_1 q_1 + p_2 q_2 + p_3 q_3.$$

- ▶ The isotropic counterpart is

$$\langle p, q \rangle_i = p_1 q_1 + p_2 q_2.$$



- ▶ Inner product of two vectors $p, q \in R^3$ is

$$\langle p, q \rangle = p_1 q_1 + p_2 q_2 + p_3 q_3.$$

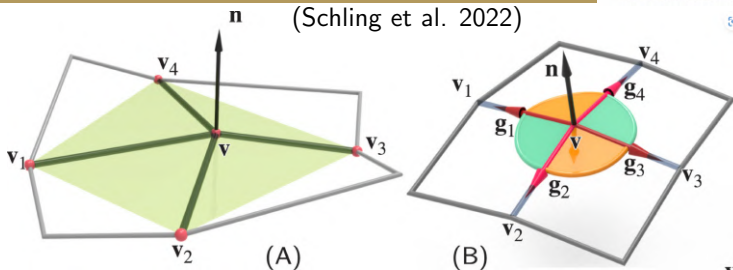
- ▶ The isotropic counterpart is

$$\langle p, q \rangle_i = p_1 q_1 + p_2 q_2.$$

- ▶ Inner Product Transformation:

$$\langle p, q \rangle_\varepsilon = p_1 q_1 + p_2 q_2 + \varepsilon p_3 q_3,$$

where ε is gradually increased from $\varepsilon = 0$ to $\varepsilon = 1$.



- Unit normal at the star vertex (\mathbf{v}):

$$\mathbf{n} \cdot (\mathbf{v}_3 - \mathbf{v}_1) = 0, \quad \mathbf{n} \cdot (\mathbf{v}_4 - \mathbf{v}_2) = 0 \quad \text{and} \quad \|\mathbf{n}\|^2 = 1.$$

- $\mathbf{v}_1, \mathbf{v}, \mathbf{v}_3$ is part of an asymptotic polyline if:

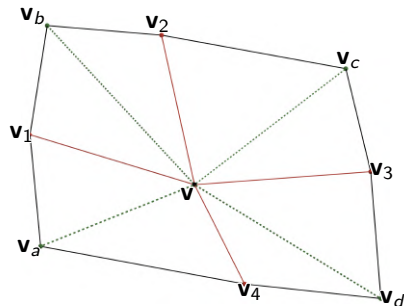
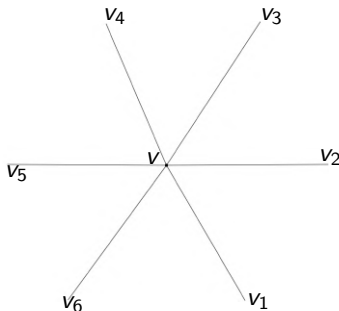
$$\mathbf{n} \cdot (\mathbf{v} - \mathbf{v}_1) = 0, \quad \text{and} \quad \mathbf{n} \cdot (\mathbf{v} - \mathbf{v}_3) = 0.$$

- $\mathbf{v}_2, \mathbf{v}, \mathbf{v}_4$ is part of a geodesic polyline if $\mathbf{v} - \mathbf{v}_2, \mathbf{v} - \mathbf{v}_4, \mathbf{n}$ are coplanar:

$$\mathbf{n}_g \cdot (\mathbf{v} - \mathbf{v}_2) = 0, \quad \mathbf{n}_g \cdot (\mathbf{v} - \mathbf{v}_4) = 0, \quad \mathbf{n} \cdot \mathbf{n}_g = 0 \quad \text{and} \quad \|\mathbf{n}_g\|^2 = 1.$$

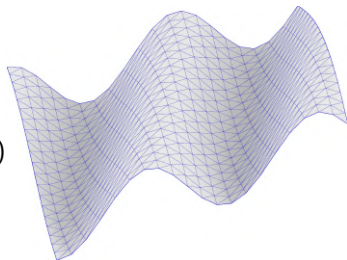


- ▶ Optimizing through the special dot product $\langle, \rangle_\varepsilon$ from $\varepsilon = 0$ to $\varepsilon = 1$.
- ▶ $\min E_{ggg} = \lambda_{fair} E_{fair} + \lambda_{glide} E_{glide} + \lambda_{geod} E_{geod}$
- ▶ $\min E_{AGAG} = \lambda_{fair} E_{fair} + \lambda_{glide} E_{glide} + \lambda_{geod} E_{geod} + \lambda_{asy} E_{asy}$
- ▶ The Gauss-Newton method with Levenberg-Marquardt regularization.

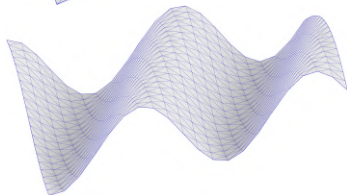




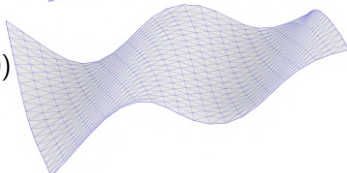
Isotropic GGG ($\epsilon = 0.0$)



$\epsilon = 0.3$

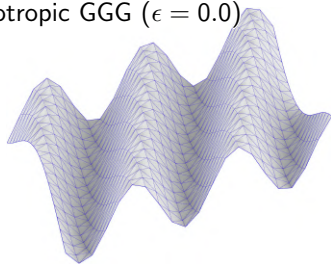


Euclidean GGG ($\epsilon = 1.0$)

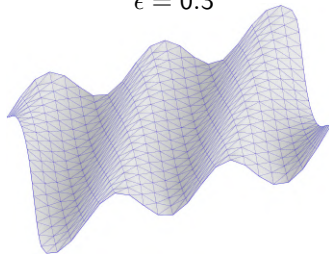




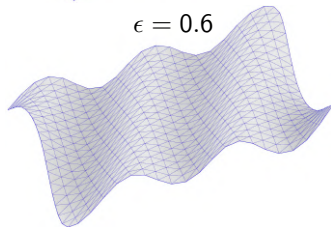
Isotropic GGG ($\epsilon = 0.0$)



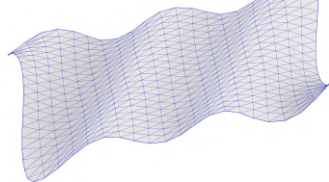
$\epsilon = 0.3$



$\epsilon = 0.6$

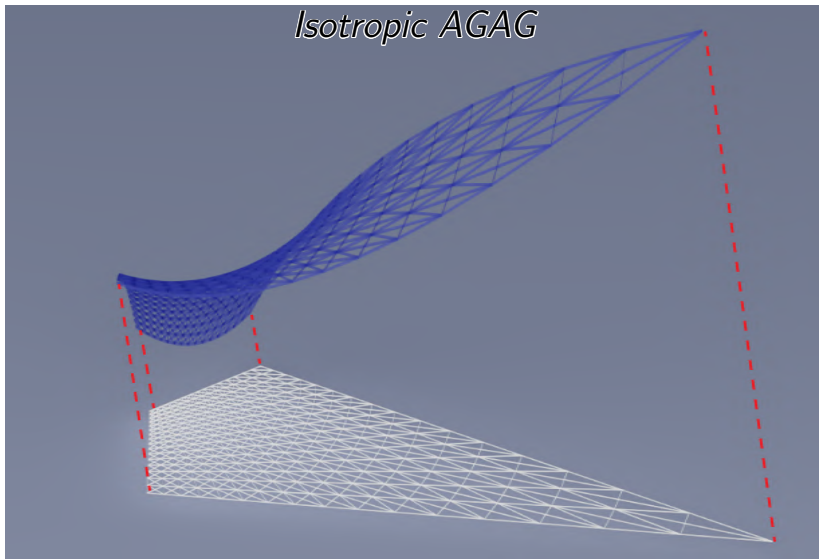


Euclidean GGG ($\epsilon = 1.0$)



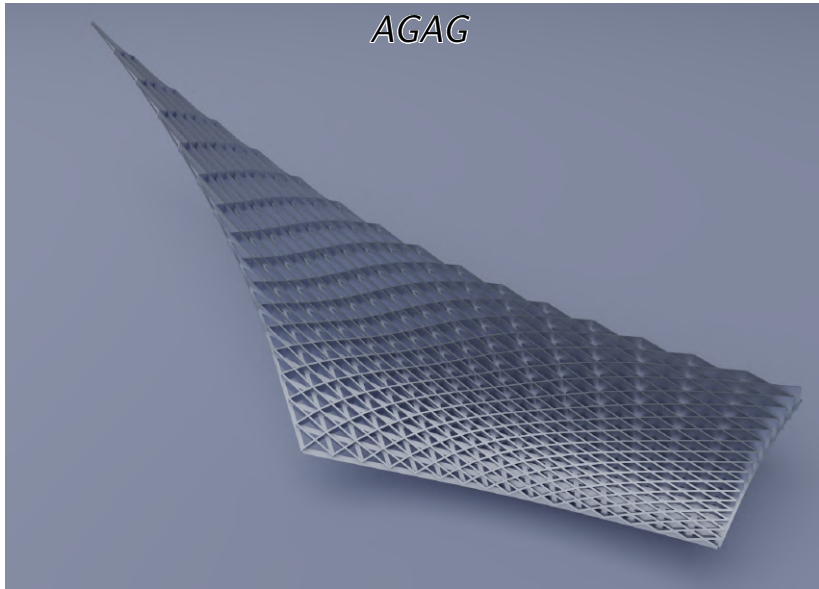


Isotropic AGAG





AGAG



The End:)



(Art Museum in Cagliari, Italy by Zaha Hadid)