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> restart:with(FGb) :
Path set to c:\Programme\Maple 10\bin.win\libfgbint.so
  FGb/Maple interface package Version 1.26
  JC Faugere (jcf@calfor.lip6.fr)
  Type ?FGb for documentation
>
> # For the given input parameters we get:
> Omega2:=23534*I*f1*e3+40344*I*e1*e3-11286*e3^2+50430*e1*e3+40344
*e2*e3+23534*f0*e1-23534*f3*e2+23534*f2*e3+15610*e2^2+15610*e1^2
-50430*I*e2*e3-63608*I*e3^2+17080*I*e2^2+17080*I*e1^2-23534*I*f0
*e2-23534*I*f3*e1;

Ω2 := 23534 I f1 e3 + 17080 I e1^2 - 11286 e3^2 + 50430 e1 e3 + 40344 e2 e3 + 23534 f0 e1
      - 23534 f3 e2 + 23534 f2 e3 + 15610 e2^2 + 15610 e1^2 - 50430 I e2 e3 - 23534 I f0 e2
      + 40344 I e1 e3 + 17080 I e2^2 - 63608 I e3^2 - 23534 I f3 e1
> Omega3:=-23534*I*f1*e3-11286*e3^2+50430*e1*e3+40344*e2*e3+23534*
f0*e1-23534*f3*e2+23534*f2*e3+15610*e2^2+15610*e1^2-40344*I*e1*e
3+50430*I*e2*e3+63608*I*e3^2-17080*I*e2^2-17080*I*e1^2+23534*I*f
0*e2+23534*I*f3*e1;

Ω3 := -23534 I f1 e3 - 11286 e3^2 + 50430 e1 e3 + 40344 e2 e3 + 23534 f0 e1 - 23534 f3 e2
      + 23534 f2 e3 + 15610 e2^2 + 15610 e1^2 - 17080 I e1^2 + 50430 I e2 e3 + 23534 I f0 e2
      - 40344 I e1 e3 - 17080 I e2^2 + 63608 I e3^2 + 23534 I f3 e1
> Omega4:=574*f0*e3-574*f2*e1+574*f1*e2-1804*e1*e3-2788*e2*e3-700*
e1^2-700*e2^2-700*e3^2;

Ω4 :=
      574 f0 e3 - 574 f2 e1 + 574 f1 e2 - 1804 e1 e3 - 2788 e2 e3 - 700 e1^2 - 700 e2^2 - 700 e3^2
> Pi5:=26600*e1^2+141204*f0*e1+70602*f2*e1-47068*f3*e1+26600*e2^2+
70602*f0*e3+47068*f0*e2+47068*f1*e3+26600*e3^2-70602*f1*e2+14120
4*f3*e2-141204*f2*e3;

π5 := 26600 e1^2 + 141204 f0 e1 + 70602 f2 e1 - 47068 f3 e1 + 26600 e2^2 + 70602 f0 e3
      + 47068 f0 e2 + 47068 f1 e3 + 26600 e3^2 - 70602 f1 e2 + 141204 f3 e2 - 141204 f2 e3
> # Lambda is the sphere condition:
> Lambda:=-4*f2*e3*x+2*Y*y*e1^2+2*Y*y*e3^2-4*e1*y*f3+4*e1*z*f2+e1^
2*X^2+e2^2*X^2+e3^2*X^2+e1^2*Y^2+e2^2*Y^2+e3^2*Y^2+e1^2*x^2+x^2*
e2^2+x^2*e3^2+e1^2*y^2+e2^2*y^2+y^2*e3^2+e1^2*z^2+z^2*e2^2+4*f0^
2+4*f3^2+4*f2^2+4*f1^2-4*Y*e1*e2*x-4*X*e1*e2*y-4*X*e1*e3*z-4*Y*
e2*e3*z-4*Z*e1*e3*x-4*Z*e2*e3*y-4*X*f0*e1+4*X*f3*e2-4*X*f2*e3-4*Y
*f3*e1-4*Y*f0*e2+4*Y*f1*e3+4*e1*x*f0+4*f3*e2*x-2*X*x*e1^2+2*X*x*
e2^2+2*X*x*e3^2+4*f0*e2*y+4*f1*e3*y-2*Y*y*e2^2-4*f1*e2*z+4*f0*e3
*z+2*Z*z*e2^2+4*Z*f2*e1-4*Z*f1*e2-4*Z*f0*e3+2*Z*z*e1^2-2*Z*z*e3^
2+e3^2*z^2+e1^2*z^2+e2^2*z^2+e3^2*z^2-e1^2*R^2-e2^2*R^2-e3^2*R^2
;

Λ := -4 Z f1 e2 + e1^2 X^2 + e2^2 X^2 + e3^2 X^2 + e1^2 Y^2 + e2^2 Y^2 + e3^2 Y^2 + e1^2 x^2 + x^2 e2^2 + x^2 e3^2
      + e1^2 y^2 + e2^2 y^2 + y^2 e3^2 + e1^2 z^2 + z^2 e2^2 + e3^2 z^2 + e1^2 Z^2 + e2^2 Z^2 + e3^2 Z^2 - e1^2 R^2 - e2^2 R^2

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$$\begin{aligned}
& -e^3 R^2 - 4f_2 e_3 x + 2Y y e l^2 + 2Y y e^3 - 4e l y f_3 + 4e l z f_2 + 4f_0^2 + 4f_3^2 + 4f_2^2 + 4f_1^2 \\
& - 4Y e l e_2 x - 4X e l e_2 y - 4X e l e_3 z - 4Y e_2 e_3 z - 4Z e l e_3 x - 4Z e_2 e_3 y - 4X f_0 e l \\
& + 4X f_3 e_2 - 4X f_2 e_3 - 4Y f_3 e l - 4Y f_0 e_2 + 4Y f_1 e_3 + 4e l x f_0 + 4f_3 e_2 x - 2X x e l^2 \\
& + 2X x e^2 + 2X x e^3 + 4f_0 e_2 y + 4f_1 e_3 y - 2Y y e^2 - 4f_1 e_2 z + 4f_0 e_3 z + 2Z z e^2 \\
& + 4Z f_2 e l - 4Z f_0 e_3 + 2Z z e l^2 - 2Z z e^3
\end{aligned}$$

> # where R denotes the leg length, (X,Y,Z) are the fixed coordinates of the base anchor point and (x,y,z) are the coordinates of the corresponding platform anchor point with respect to the moving system.

>

> # Computation of the f0, ..., f3:

> fs:=solve({e1\*f1+e2\*f2+e3\*f3, Omega2, Omega3, Omega4}, {f0, f1, f2, f3});

$$\begin{aligned}
fs := \{ & f_1 = (48614 e^2 e_3 - 8540 e l^2 e_3 + 39565 e_2 e_3^2 + 31804 e_3^3 - 20172 e l e_3^2 \\
& + 14350 e_2 e l^2 + 14350 e_2^3 + 36982 e l e_2 e_3) / (11767 (e^2 + e^3 + e l^2)), f_2 = ( \\
& -57154 e l e_2 e_3 - 14350 e l^3 - 14350 e l e_2^2 - 44787 e l^2 e_3 - 39565 e l e_3^2 + 5643 e_3^3 \\
& - 7805 e_2^2 e_3 - 20172 e_2 e_3^2) / (11767 (e^2 + e^3 + e l^2)), f_0 = 5 (8525 e l e_3^2 \\
& + 5070 e_2 e_3^2 - 1561 e l e_2^2 - 2173 e_2^2 e_3 - 2173 e l^2 e_3 - 1561 e l^3 + 1708 e_2^3 + 2870 e_3^3 \\
& + 1708 e_2 e l^2) / (11767 (e^2 + e^3 + e l^2)), f_3 = -(-8540 e l e_2^2 - 7805 e_2 e l^2 \\
& + 5643 e_2 e_3^2 - 7805 e_2^3 - 20172 e_2^2 e_3 - 8540 e l^3 + 31804 e l e_3^2 - 20172 e l^2 e_3) / ( \\
& 11767 (e^2 + e^3 + e l^2)) \}
\end{aligned}$$

> assign(fs);

> F:=8525\*e3^2\*e1+5070\*e3^2\*e2+1708\*e2\*e1^2+1708\*e2^3-1561\*e1\*e2^2-2173\*e2^2\*e3-1561\*e1^3-2173\*e1^2\*e3+2870\*e3^3;

$$\begin{aligned}
F := & 8525 e l e_3^2 + 5070 e_2 e_3^2 - 1561 e l e_2^2 - 2173 e_2^2 e_3 - 2173 e l^2 e_3 - 1561 e l^3 \\
& + 1708 e_2^3 + 2870 e_3^3 + 1708 e_2 e l^2
\end{aligned}$$

>

> # Test:

> gcd(F, factor( numer(Pi5) ))-F;

0

> gcd(F, factor( numer(f0) ))-F;

0

>

> # Now we make the following ansatz:

> Gamma:=numer(simplify(Lambda)):nops(%);

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> ansatz:=simplify(F\*(eta1\*e1+eta2\*e2+eta3\*e3)-Gamma):

>

> # The set of equations implied by the coefficients with respect to e1,e2,e3 read as follows:

> c400:=coeff(coeff(coeff(ansatz, e1, 4), e2, 0), e3, 0);

$$c400 := -808500 - 164738 Y y + 164738 X x + 239120 Y + 401800 Z - 82369 x^2 + 239120 y$$

$$+ 218540 x + 401800 z - 218540 X - 82369 Y^2 - 82369 z^2 - 164738 Z z - 1561 \eta_1$$

$$- 82369 y^2 - 82369 Z^2 + 82369 R^2 - 82369 X^2$$

> **c040 := coeff(coeff(coeff(ansatz, e1, 0), e2, 4), e3, 0);**

$$c040 := -808500 + 164738 Y y - 164738 X x - 239120 y + 401800 z - 82369 Y^2 - 218540 x$$

$$+ 401800 Z - 218540 X + 239120 Y - 164738 Z z + 1708 \eta_2 + 82369 R^2 - 82369 x^2$$

$$- 82369 y^2 - 82369 z^2 - 82369 Z^2 - 82369 X^2$$

> **c004 := coeff(coeff(coeff(ansatz, e1, 0), e2, 0), e3, 4);**

$$c004 := 164738 Z z - 2972660 - 164738 X x - 164738 Y y + 82369 R^2 - 82369 x^2 - 82369 X^2$$

$$- 890512 y - 890512 Y + 158004 x - 82369 y^2 + 401800 Z - 82369 Z^2 - 401800 z - 82369 z^2$$

$$+ 158004 X - 82369 Y^2 + 2870 \eta_3$$

> **c013 := coeff(coeff(coeff(ansatz, e1, 0), e2, 1), e3, 3);**

$$c013 := 5070 \eta_3 + 2870 \eta_2 - 706020 Y + 180712 z - 564816 X - 564816 x + 1600312 Z$$

$$+ 329476 Z y + 329476 Y z - 7177952 - 1509620 y$$

> **c103 := coeff(coeff(coeff(ansatz, e1, 1), e2, 0), e3, 3);**

$$c103 := -1509620 x - 706020 X + 564816 Y - 1351504 z + 8525 \eta_3 + 1035496 Z + 2870 \eta_1$$

$$+ 564816 y + 1204744 + 329476 X z + 329476 Z x$$

> **c310 := coeff(coeff(coeff(ansatz, e1, 3), e2, 1), e3, 0);**

$$c310 := -1561 \eta_2 + 1708 \eta_1 + 437080 y + 329476 X y + 329476 Y x - 478240 x$$

> **c301 := coeff(coeff(coeff(ansatz, e1, 3), e2, 0), e3, 1);**

$$c301 := -2173 \eta_1 - 706020 X + 564816 Y + 1035496 Z - 1561 \eta_3 - 97580 x + 1472576 z$$

$$+ 564816 y + 329476 X z + 329476 Z x - 4282040$$

> **c130 := coeff(coeff(coeff(ansatz, e1, 1), e2, 3), e3, 0);**

$$c130 := -1561 \eta_2 + 1708 \eta_1 + 437080 y + 329476 X y + 329476 Y x - 478240 x$$

> **c031 := coeff(coeff(coeff(ansatz, e1, 0), e2, 3), e3, 1);**

$$c031 := -2173 \eta_2 + 1122072 z - 97580 y + 1708 \eta_3 - 564816 x + 1600312 Z - 564816 X$$

$$- 706020 Y + 329476 Z y + 329476 Y z - 3627680$$

> **c022 := coeff(coeff(coeff(ansatz, e1, 0), e2, 2), e3, 2);**

$$c022 := -2173 \eta_3 + 5070 \eta_2 - 164738 X^2 - 9731900 - 164738 Y^2 - 164738 x^2 - 164738 y^2$$

$$- 164738 z^2 - 164738 Z^2 + 164738 R^2 - 2070992 y + 1412040 z - 60536 x + 803600 Z$$

$$- 60536 X - 651392 Y - 329476 X x$$

> **c202 := coeff(coeff(coeff(ansatz, e1, 2), e2, 0), e3, 2);**

$$c202 := -5213372 - 164738 X^2 - 164738 Y^2 - 164738 x^2 - 164738 y^2 - 164738 z^2$$

$$- 164738 Z^2 + 164738 R^2 - 329476 Y y - 651392 Y + 803600 Z - 2447536 x + 1412040 z$$

$$- 651392 y - 2173 \eta_3 - 60536 X + 8525 \eta_1$$

> **c220 := coeff(coeff(coeff(ansatz, e1, 2), e2, 2), e3, 0);**

$$c220 := -1617000 - 164738 X^2 - 164738 Y^2 - 164738 x^2 - 164738 y^2 - 164738 z^2$$

$$- 164738 Z^2 + 164738 R^2 - 329476 Z z + 803600 z + 803600 Z - 437080 X + 478240 Y$$

$$+ 1708 \eta_2 - 1561 \eta_1$$

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> c211:=coeff(coeff(coeff(ansatz,e1,2),e2,1),e3,1);
c211 := -2173 η2 + 1122072 z - 97580 y + 1708 η3 - 564816 x + 1600312 Z - 564816 X
      - 706020 Y + 329476 Z y + 329476 Y z - 3627680
> c121:=coeff(coeff(coeff(ansatz,e1,1),e2,2),e3,1);
c121 := -2173 η1 - 706020 X + 564816 Y + 1035496 Z - 1561 η3 - 97580 x + 1472576 z
      + 564816 y + 329476 X z + 329476 Z x - 4282040
> c112:=coeff(coeff(coeff(ansatz,e1,1),e2,1),e3,2);
c112 := 329476 Y x - 2387000 y + 329476 X y - 10059104 + 5070 η1 + 8525 η2 - 1419600 x
>
> # Gröbner base elimination of X,Y,Z,eta1,eta2,eta3,R
> GBE:=fgb_gbasis_elim([c400,c040,c004,c310,c301,c130,c031,c013,c1
03,c112,c121,c211,c022,c202,c220],0,[X,Y,Z,eta1,eta2,eta3,R],[X,
Y,Z,x,y,z,eta1,eta2,eta3,R]):
> Hilbert:=fgb_hilbert(GBE,0,[],[op(indets(GBE))],T);
      Hilbert := [4 T3 + 3 T2 + 2 T + 1, 1]
> # Dimension of GBE:
> Hilbert[2];
      1
> # Degree of GBE:
> subs(T=1,Hilbert[1]);
      10
>
> # Isotropic planes through p are given by:
> epsilon1:=91*x-84*y+147*I*y-98*I*z-126*z-122+714*I;
      ε1 := 91 x - 84 y + 147 I y - 98 I z - 126 z - 122 + 714 I
> epsilon2:=91*x-84*y-147*I*y+98*I*z-126*z-122-714*I;
      ε2 := 91 x - 84 y - 147 I y + 98 I z - 126 z - 122 - 714 I
>
> x:=solve(epsilon1,x);
      x :=  $\frac{12 y}{13} - \frac{21}{13} I y + \frac{14}{13} I z + \frac{18 z}{13} + \frac{122}{91} - \frac{102}{13} I$ 
> g1:=0:
> for i from 1 to nops(GBE) do
> g:=numer(factor(simplify(GBE[i]))):
> g1:=gcd(g1,g):
> end do:
> x:='x':
>
>
>
> x:=solve(epsilon2,x);
      x :=  $\frac{12 y}{13} + \frac{21}{13} I y - \frac{14}{13} I z + \frac{18 z}{13} + \frac{122}{91} + \frac{102}{13} I$ 
> g2:=0:

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> for i from 1 to nops(GBE) do
> g:=numer(factor(simplify(GBE[i]))):
> g2:=gcd(g2,g):
> end do:
[ > x:='x':
[ >
[ > factor(numer(g1));
(-14 z + 102 + 21 y) (274400 y3 + 9573816 I y z + 3927840 y2 + 817369 I z2 - 30870 y2 z
- 1840195 I y2 + 15910300 y + 3374238 y z - 15809850 I y - 408170 I z3 - 1165514 y z2
+ 13169366 z + 17761620 - 29479660 I + 20061237 I z + 984410 I y2 z - 5472908 z2
+ 113190 z3 - 115248 I y z2)
[ > factor(numer(g2));
(-14 z + 102 + 21 y) (274400 y3 - 9573816 I y z + 3927840 y2 - 817369 I z2 - 30870 y2 z
+ 1840195 I y2 + 15910300 y + 3374238 y z + 15809850 I y + 408170 I z3 - 1165514 y z2
+ 13169366 z + 17761620 + 29479660 I - 20061237 I z - 984410 I y2 z - 5472908 z2
+ 113190 z3 + 115248 I y z2)
[ > # End.

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