

```
> restart: with(plots): with(LinearAlgebra):
```

Prozeduren für Quaternionen und duale Quaternionen

Schreiben Quaternion als 4er Vektor

Prozedur für Quaternionenmultiplikation

```
> Qmult:=proc(a,b):  
    simplify(<a[1]*b[1]-a[2]*b[2]-a[3]*b[3]-a[4]*b[4],  
            a[1]*b[2]+b[1]*a[2]+a[3]*b[4]-b[3]*a[4],  
            a[1]*b[3]+b[1]*a[3]+a[4]*b[2]-b[4]*a[2],  
            a[1]*b[4]+b[1]*a[4]+a[2]*b[3]-b[2]*a[3]>);  
end proc:
```

Prozedur für die konjugierte Quaternion

```
> Qkon:=proc(a):  
    <a[1],-a[2],-a[3],-a[4]>;  
end proc:
```

Prozedur für die inverse Quaternion

```
> Qinv:=proc(a):  
    1/Norm(a,2)^2*Qkon(a):  
end proc:
```

Duale Quaternion ist durch ein Quaternionenpaar gegeben

Prozedur für Produkt dualer Quaternionen

```
> DQmult:=proc(a,a_,b,b_) :  
> Qmult(a,b),VectorAdd(Qmult(a_,b),Qmult(a,b_));  
> end proc:
```

Prozedur für die konjugierte duale Quaternion

```
> DQkon:=proc(a,a_) :  
    Qkon(a),Qkon(a_) ;  
end proc:
```

Prozedur für die dual konjugierte duale Quaternion

```
> DQdkon:=proc(a,a_) :  
    a,VectorScalarMultiply(a_,-1) ;  
end proc:
```

Prozedur für die sowohl konjugierte als auch dual konjugierte duale Quaternion

```
> DQkdk:=proc(a,a_) :  
    Qkon(a),VectorScalarMultiply(Qkon(a_),-1) ;  
end proc:
```

Angabe des 6R Roboters mit Handgelenk in der Ausgangslage

└─ Achsen (pi,pi_) in Ausgangslage

```
> a2:=3:b2:=1:
> a3:=3:b3:=4:x3:=3:y3:=4:z3:=7:
> a4:=2:b4:=1:x4:=7:y4:=-2:z4:=11:
> a5:=0:b5:=1:
> a6:=2:b6:=3:
```

```
> p1:=<1,0,0>: p1:=VectorScalarMultiply(p1,1/Norm(p1,2)):P1:=<0,0,
0>:p1_:=CrossProduct(P1,p1):
> p2:=<a2,b2,0>:p2:=VectorScalarMultiply(p2,1/Norm(p2,2)):P2:=<0,0,
1>:p2_:=CrossProduct(P2,p2):
> p3:=<a3,b3,0>:p3:=VectorScalarMultiply(p3,1/Norm(p3,2)):P3:=<x3,
y3,z3>:p3_:=CrossProduct(P3,p3):
> p4:=<a4,b4,0>:p4:=VectorScalarMultiply(p4,1/Norm(p4,2)):P4:=<x4,
y4,z4>:p4_:=CrossProduct(P4,p4):
> p5:=<a5,b5,0>:p5:=VectorScalarMultiply(p5,1/Norm(p5,2)):P5:=<x4,
y4,z4>:p5_:=CrossProduct(P5,p5):
> p6:=<a6,b6,0>:p6:=VectorScalarMultiply(p6,1/Norm(p6,2)):P6:=<x4,
y4,z4>:p6_:=CrossProduct(P6,p6):
```

└─ Bemerke, dass der Handgelenkspunkt die Rastkoordinaten (x4,y4,z4) in der Ausgangslage hat.

└─ Drehungen um Achsen in dualen Quaternionen

```
> DQ1:=<cos(theta1/2),sin(theta1/2)*p1[1],sin(theta1/2)*p1[2],sin
(theta1/2)*p1[3]>,<0,sin(theta1/2)*p1_[1],sin(theta1/2)*p1_[2],
sin(theta1/2)*p1_[3]>:
> DQ2:=<cos(theta2/2),sin(theta2/2)*p2[1],sin(theta2/2)*p2[2],sin
(theta2/2)*p2[3]>,<0,sin(theta2/2)*p2_[1],sin(theta2/2)*p2_[2],
sin(theta2/2)*p2_[3]>:
> DQ3:=<cos(theta3/2),sin(theta3/2)*p3[1],sin(theta3/2)*p3[2],sin
(theta3/2)*p3[3]>,<0,sin(theta3/2)*p3_[1],sin(theta3/2)*p3_[2],
sin(theta3/2)*p3_[3]>:
> DQ4:=<cos(theta4/2),sin(theta4/2)*p4[1],sin(theta4/2)*p4[2],sin
(theta4/2)*p4[3]>,<0,sin(theta4/2)*p4_[1],sin(theta4/2)*p4_[2],
sin(theta4/2)*p4_[3]>:
> DQ5:=<cos(theta5/2),sin(theta5/2)*p5[1],sin(theta5/2)*p5[2],sin
(theta5/2)*p5[3]>,<0,sin(theta5/2)*p5_[1],sin(theta5/2)*p5_[2],
sin(theta5/2)*p5_[3]>:
> DQ6:=<cos(theta6/2),sin(theta6/2)*p6[1],sin(theta6/2)*p6[2],sin
(theta6/2)*p6[3]>,<0,sin(theta6/2)*p6_[1],sin(theta6/2)*p6_[2],
```

`sin(theta6/2)*p6_[3]>:`

Generierung einer Endeffektorstellung

`> Pose:=DQmult(DQmult(DQmult(DQmult(DQmult(DQ1,DQ2),DQ3),DQ4),DQ5),DQ6):`

`> Given1:=(simplify(subs(theta1=Pi/2,theta2=Pi/3,theta3=-Pi/2,theta4=-Pi/3,theta5=Pi/2,theta6=-Pi/2,Pose[1]))) ;`

`Given1 :=`

$$\left[\begin{array}{l} \frac{((25\sqrt{15} + 60)\sqrt{2} - 10\sqrt{15} + 180)\sqrt{13}}{2600} + \frac{9}{20} + \frac{(-52\sqrt{15} + 195)\sqrt{2}}{2600} \\ \frac{((26\sqrt{2} - 45)\sqrt{15} - 30\sqrt{2} - 225)\sqrt{13}}{2600} + \frac{9}{40} + \frac{(104\sqrt{2} - 65)\sqrt{15}}{2600} \\ \frac{(-45\sqrt{2} + 30\sqrt{15} - 240)\sqrt{13}}{2600} + \frac{3}{20} + \frac{(39\sqrt{15} + 260)\sqrt{2}}{2600} \\ \frac{((-18\sqrt{2} + 15)\sqrt{15} + 40\sqrt{2} - 75)\sqrt{13}}{2600} - \frac{3}{40} + \frac{(78\sqrt{2} - 195)\sqrt{15}}{2600} \end{array} \right]$$

(1)

`> Given2:=(simplify(subs(theta1=Pi/2,theta2=Pi/3,theta3=-Pi/2,theta4=-Pi/3,theta5=Pi/2,theta6=-Pi/2,Pose[2]))) ;`

`Given2 :=` $\left[\left[\frac{((-134\sqrt{2} + 63)\sqrt{15} + 1075\sqrt{2} - 5265)\sqrt{13}}{5200} \right. \right.$

$$\left. + \frac{(1261\sqrt{2} - 1833)\sqrt{15}}{5200} - \frac{69\sqrt{2}}{100} + \frac{129}{80} \right],$$

$$\left[\frac{((-317\sqrt{2} - 615)\sqrt{15} + 344\sqrt{2} + 3345)\sqrt{13}}{5200} + \frac{(806\sqrt{2} + 3081)\sqrt{15}}{5200} \right.$$

$$\left. - \frac{213\sqrt{2}}{400} - \frac{201}{80} \right],$$

$$\left[\frac{((663\sqrt{2} - 659)\sqrt{15} + 300\sqrt{2} - 5205)\sqrt{13}}{5200} + \frac{(-702\sqrt{2} + 39)\sqrt{15}}{5200} \right.$$

$$\left. + \frac{207\sqrt{2}}{400} - \frac{57}{80} \right],$$

$$\left[\frac{((-644\sqrt{2} - 485)\sqrt{15} - 1017\sqrt{2} - 6015)\sqrt{13}}{5200} + \frac{(117\sqrt{2} - 1027)\sqrt{15}}{5200} \right.$$

$$\left. - \frac{33\sqrt{2}}{200} + \frac{57}{80} \right]$$

(2)

`> Given:=Given1,Given2:`

Rückwärtskinematik

`> DQ1n:=<c1,s1*p1[1],s1*p1[2],s1*p1[3]>,<0,s1*p1_[1],s1*p1_[2],s1*`

$$\begin{aligned}
& -1650 sI^2) \sqrt{15} + (-375 cI^2 + 14850 cI sI + 375 sI^2) \sqrt{2} - 2650 cI^2 + 19736 cI sI \\
& + 2650 sI^2) \sqrt{13}) \\
& + \frac{((-5029 cI^2 - 24240 cI sI + 5029 sI^2) \sqrt{2} - 800 cI^2 - 1856 cI sI + 800 sI^2) \sqrt{15}}{13000} \\
& + \frac{(5760 cI^2 - 7200 cI sI - 5760 sI^2) \sqrt{2}}{13000} - \frac{37 cI^2}{5} + \frac{1109 cI sI}{250} + \frac{37 sI^2}{5} \\
& + \frac{1}{13000} (((2454 cI^2 + 1590 cI sI - 2454 sI^2) \sqrt{2} - 1650 cI^2 - 1350 cI sI \\
& + 1650 sI^2) \sqrt{15} + (375 cI^2 - 14850 cI sI - 375 sI^2) \sqrt{2} + 2650 cI^2 - 19736 cI sI \\
& - 2650 sI^2) \sqrt{13}) \\
& + \frac{((-4773 cI^2 - 25680 cI sI + 4773 sI^2) \sqrt{2} + 800 cI^2 + 1856 cI sI - 800 sI^2) \sqrt{15}}{13000} \\
& + \frac{(-5760 cI^2 + 7200 cI sI + 5760 sI^2) \sqrt{2}}{13000} \Big], \\
& \Big[\frac{1}{13000} ((((-795 cI^2 + 4908 cI sI + 795 sI^2) \sqrt{2} + 675 cI^2 - 3300 cI sI \\
& - 675 sI^2) \sqrt{15} + (7425 cI^2 + 750 cI sI - 7425 sI^2) \sqrt{2} + 9868 cI^2 + 5300 cI sI \\
& - 9868 sI^2) \sqrt{13}) \\
& + \frac{1}{13000} (((-12120 cI^2 + 10058 cI sI + 12120 sI^2) \sqrt{2} - 928 cI^2 + 1600 cI sI \\
& + 928 sI^2) \sqrt{15}) + \frac{(-3600 cI^2 - 11520 cI sI + 3600 sI^2) \sqrt{2}}{13000} + \frac{1109 cI^2}{500} \\
& + \frac{74 cI sI}{5} - \frac{1109 sI^2}{500} + \frac{1}{13000} (((795 cI^2 - 4908 cI sI - 795 sI^2) \sqrt{2} \\
& - 675 cI^2 + 3300 cI sI + 675 sI^2) \sqrt{15} + (-7425 cI^2 - 750 cI sI + 7425 sI^2) \sqrt{2} \\
& - 9868 cI^2 - 5300 cI sI + 9868 sI^2) \sqrt{13}) \\
& + \frac{1}{13000} (((-12840 cI^2 + 9546 cI sI + 12840 sI^2) \sqrt{2} + 928 cI^2 - 1600 cI sI \\
& - 928 sI^2) \sqrt{15}) + \frac{(3600 cI^2 + 11520 cI sI - 3600 sI^2) \sqrt{2}}{13000} \Big] \Big]
\end{aligned}$$

```

> links:=DQmult(DQ2n,DQ3n) :
=
> rechts:=DQmult(DQkdk(DQ3n),DQkdk(DQ2n)) :
=
> finale:=DQmult(DQmult(links,HG),rechts) ;

```

$$\begin{aligned}
\text{finale} := & \left[\begin{array}{c} (c^3 + s^3) (c^2 + s^2) \\ 0 \\ 0 \\ 0 \end{array} \right], \left[\begin{array}{c} \left[\begin{array}{c} \frac{21 c_2 s_2 \left(c^3 - \frac{136}{105} c_3 s_3 - \frac{3}{7} s^3 \right) \sqrt{10}}{10} + \frac{(1750 c^3 + 3000 c_3 s_3 - 970 s^3) c^2}{250} \\ + \frac{22 s^2 \left(c^3 + \frac{21}{22} c_3 s_3 + \frac{37}{275} s^3 \right)}{5} - \frac{c_2 s_2 (c^3 - 13 s^3) \sqrt{10}}{10} \\ - \frac{28 \left(c^2 + \frac{7 s^2}{20} \right) c_3 s_3}{5} \end{array} \right] \\ \left[\begin{array}{c} - \frac{63 c_2 s_2 \left(c^3 - \frac{136}{105} c_3 s_3 - \frac{3}{7} s^3 \right) \sqrt{10}}{10} \\ + \frac{(-500 c^3 - 2250 c_3 s_3 + 1540 s^3) c^2}{250} + \frac{29 s^2 \left(c^3 + \frac{72}{29} c_3 s_3 - \frac{907}{725} s^3 \right)}{5} \\ + \frac{3 c_2 s_2 (c^3 - 13 s^3) \sqrt{10}}{10} + \frac{21 c_3 s_3 \left(c^2 - \frac{8 s^2}{5} \right)}{5} \end{array} \right] \\ \left[\begin{array}{c} - \frac{13 c_2 s_2 \left(c^3 + 3 c_3 s_3 - \frac{43}{25} s^3 \right) \sqrt{10}}{5} + \frac{(1375 c^3 - 1700 c_3 s_3 - 500 s^3) c^2}{125} \\ - 10 s^2 \left(c^3 - \frac{34}{25} c_3 s_3 - \frac{1}{2} s^3 \right) + \frac{91 c_2 c_3 s_2 \sqrt{10} s_3}{25} - 6 s^2 s^3 + 7 c^2 s^3 \\ + s^2 c^3 \end{array} \right] \end{array} \right] \quad (5)
\end{aligned}$$

$$\begin{aligned}
& \text{> lang:=factor(Norm(finale[2],2,conjugate=false)^2);} \\
\text{lang} := & -\frac{1}{125} \left(2 \left(325 c_2 c^3 s_2 \sqrt{10} + 520 c_2 c_3 s_2 \sqrt{10} s_3 - 559 s_2 \sqrt{10} s^3 c_2 \right. \right. \\
& - 10875 c^2 c^3 + 11900 c^2 c_3 s_3 - 3875 c^2 s^3 - 8375 s^2 c^3 + 8500 s^2 s_3 c_3 \\
& \left. \left. - 3375 s^2 s^3 \right) (c^2 + s^2) (c^3 + s^3) \right) \quad (6)
\end{aligned}$$

$$\begin{aligned}
& \text{> langHG:=factor(Norm(finaleHG[2],2,conjugate=false)^2);} \\
\text{langHG} := & \frac{(377 \sqrt{2} \sqrt{15} + 50100) (c^2 + s^2)^2}{250} \quad (7)
\end{aligned}$$

$$\begin{aligned}
& \text{eq1} := \text{simplify}(\text{numer}(\text{finaleHG}[2][2] - \text{finale}[2][2])); \\
\text{eq1} & := \left((320 c l^2 + 320 s l^2) \sqrt{3} - 1000 s_2 \left(c^3 - \frac{34}{25} c_3 s_3 + \frac{1}{5} s_3^2 \right) c_2 \right) \sqrt{10} + (\\
& -3500 c^3 - 3200 c_3 s_3 + 1940 s_3^2) c_2^2 - 2200 s_2^2 c^3 - 1120 s_2^2 s_3 c_3 - 296 s_2^2 s_3^2 \\
& - 443 c l^2 - 443 s l^2
\end{aligned} \tag{8}$$

$$\begin{aligned}
& \text{eq2} := \text{simplify}(\text{numer}(\text{finaleHG}[2][3] - \text{finale}[2][3])); \\
\text{eq2} & := \left((-377 c l^2 - 1920 c l s l + 377 s l^2) \sqrt{3} + 3000 s_2 \left(c^3 - \frac{34}{25} c_3 s_3 \right. \right. \\
& \left. \left. + \frac{1}{5} s_3^2 \right) c_2 \right) \sqrt{10} + (1000 c^3 + 2400 c_3 s_3 - 3080 s_3^2) c_2^2 - 2900 s_2^2 c^3 \\
& - 3840 s_2^2 s_3 c_3 + 3628 s_2^2 s_3^2 - 3700 c l^2 + 2218 c l s l + 3700 s l^2
\end{aligned} \tag{9}$$

$$\begin{aligned}
& \text{eq3} := \text{simplify}(\text{numer}(\text{finaleHG}[2][4] - \text{finale}[2][4])); \\
\text{eq3} & := \left((-960 c l^2 + 754 c l s l + 960 s l^2) \sqrt{3} + 1300 s_2 c_2 \left(c^3 + \frac{8}{5} c_3 s_3 \right. \right. \\
& \left. \left. - \frac{43}{25} s_3^2 \right) \right) \sqrt{10} + (-5500 c^3 + 6800 c_3 s_3 - 1500 s_3^2) c_2^2 + 4500 s_2^2 c^3 \\
& - 6800 s_2^2 s_3 c_3 + 500 s_2^2 s_3^2 + 1109 c l^2 + 7400 c l s l - 1109 s l^2
\end{aligned} \tag{10}$$

$$\begin{aligned}
& \text{eq4} := \text{simplify}(\text{numer}(\text{langHG} - \text{lang})); \\
\text{eq4} & := \left(377 (c l^2 + s l^2)^2 \sqrt{3} + 1300 s_2 (c^3 + s^3) c_2 \left(c^3 + \frac{8}{5} c_3 s_3 - \frac{43}{25} s_3^2 \right) (c_2^2 \right. \right. \\
& \left. \left. + s_2^2) \right) \sqrt{10} - 43500 \left(c^3 - \frac{476}{435} c_3 s_3 + \frac{31}{87} s_3^2 \right) (c^3 + s^3) c_2^4 - 77000 s_2^2 (c^3 \right. \\
& \left. + s^3) \left(c^3 - \frac{408}{385} c_3 s_3 + \frac{29}{77} s_3^2 \right) c_2^2 - 33500 s_2^4 c^3 + 34000 s_2^4 c^3 s_3 \right. \\
& \left. - 47000 s_2^4 c^3 s_3^2 + 34000 s_2^4 s_3^3 c_3 - 13500 s_2^4 s_3^4 + 50100 (c l^2 + s l^2)^2 \right)
\end{aligned} \tag{11}$$

$$\text{s3} := 2 * t_3 / (1 + t_3^2) : c_3 := (1 - t_3^2) / (1 + t_3^2) :$$

$$\begin{aligned}
& \text{yes1} := \text{numer}(\text{simplify}(\text{eq1}, \{s_2^2 + c_2^2 = 1, s_1^2 + c_1^2 = 1\})); \\
\text{yes1} & := -1000 \sqrt{10} c_2 s_2 t_3^4 + 320 \sqrt{3} \sqrt{10} t_3^4 - 2720 \sqrt{10} c_2 s_2 t_3^3 - 1300 c_2^2 t_3^4 \\
& + 1200 \sqrt{10} c_2 s_2 t_3^2 + 4160 c_2^2 t_3^3 + 640 \sqrt{3} \sqrt{10} t_3^2 + 2720 \sqrt{10} c_2 s_2 t_3 \\
& + 11544 c_2^2 t_3^2 - 2643 t_3^4 - 1000 c_2 s_2 \sqrt{10} - 4160 c_2^2 t_3 + 2240 t_3^3 + 320 \sqrt{10} \sqrt{3} \\
& - 1300 c_2^2 + 2330 t_3^2 - 2240 t_3 - 2643
\end{aligned} \tag{12}$$

$$\text{yes2} := \text{numer}(\text{simplify}(\text{eq2}));$$

$$\text{yes3} := \text{numer}(\text{simplify}(\text{eq3}));$$

$$\begin{aligned}
& \text{yes4} := \text{numer}(\text{simplify}(\text{eq4}, \{s_2^2 + c_2^2 = 1, s_1^2 + c_1^2 = 1\})); \\
\text{yes4} & := 1300 \sqrt{10} c_2 s_2 t_3^4 + 377 \sqrt{3} \sqrt{10} t_3^4 - 4160 \sqrt{10} c_2 s_2 t_3^3 - 10000 c_2^2 t_3^4 \\
& - 11544 \sqrt{10} c_2 s_2 t_3^2 - 27200 c_2^2 t_3^3 + 754 \sqrt{3} \sqrt{10} t_3^2 + 4160 \sqrt{10} c_2 s_2 t_3 \\
& + 12000 c_2^2 t_3^2 + 16600 t_3^4 + 1300 c_2 s_2 \sqrt{10} + 27200 c_2^2 t_3 - 68000 t_3^3 \\
& + 377 \sqrt{10} \sqrt{3} - 10000 c_2^2 + 113200 t_3^2 + 68000 t_3 + 16600
\end{aligned} \tag{13}$$

```
> degree (yes1 , t1) ; degree (yes4 , t1) ;
0
0 (14)
```

```
> factor (simplify (resultant (yes1 , yes4 , t3) ) ) ;
63468627558400 ( 3151200  $\sqrt{3}$   $\sqrt{10}$   $c^6$  + 3151200  $\sqrt{3}$   $\sqrt{10}$   $c^4 s^2$  + 777400000  $c^8$ 
+ 1554800000  $c^6 s^2$  + 777400000  $c^4 s^4$  + 1158799200  $\sqrt{10}$   $c^5 s$ 
+ 1158799200  $\sqrt{10}$   $c^3 s^3$  + 1474356000  $\sqrt{3}$   $c^2 s$  + 1474356000  $\sqrt{3}$   $c^2 s^3$ 
- 720912720  $\sqrt{3}$   $\sqrt{10}$   $c^4$  - 1440073440  $\sqrt{3}$   $\sqrt{10}$   $c^2 s^2$  + 22506484000  $c^6$ 
+ 22506484000  $c^4 s^2$  + 1019375760  $\sqrt{10}$   $c^3 s$  + 8555528436  $\sqrt{3}$   $c^3 s$ 
+ 1083882240  $\sqrt{3}$   $\sqrt{10}$   $c^2$  + 12599014694  $c^4$  - 75603813662  $s^2 c^2$ 
- 14932048560  $c^2 s \sqrt{10}$  + 28854498504  $\sqrt{3}$   $c^2 s$  + 3185447280  $\sqrt{10}$   $\sqrt{3}$ 
- 15455396368  $c^2$  - 21699552051 )2 (15)
```

```
> T:=-25616084000*s^6+777400000*s^8-1272049725-80371685020*
s^2+3551568000*2^(1/2)*3^(1/2)*5^(1/2)+1158799200*c2*s^5*5^
(1/2)*2^(1/2)-711459120*s^4*2^(1/2)*3^(1/2)*5^(1/2)+1474356000*
c2*s^5*3^(1/2)+1474356000*c2^3*s^2*3^(1/2)-11504240436*c2*s^2*3*
3^(1/2)+38884382940*c2*s^2*3^(1/2)-12753873600*c2*s^2*5^(1/2)*2^
(1/2)-51542529662*c2^2*s^2+84782866694*s^4+1158799200*c2^3*
s^2*3*5^(1/2)*2^(1/2)-1436922240*c2^2*s^2*5^(1/2)*2^(1/2)*3^(1/2)
-3151200*c2^2*s^2*4*5^(1/2)*2^(1/2)*3^(1/2)-3336974160*c2*s^2*3*5^
(1/2)*2^(1/2)+348489600*2^(1/2)*3^(1/2)*5^(1/2)*s^2-3151200*
s^2*6*2^(1/2)*3^(1/2)*5^(1/2)+777400000*c2^4*s^4-25616084000*
c2^2*s^2*4+1554800000*c2^2*s^2*6:
```

```
> degree (T , c2) ; degree (T , s2) ;
4
8 (16)
```

```
> hilf2:=c2^2+s2^2-1;
hilf2 := c2 + s2 - 1 (17)
```

```
> weg:=numer (factor (resultant (T , hilf2 , s2) ) ) ;
weg := -9 ( 2468012977277191511 + 39496537186164740  $\sqrt{30}$  ) ( 4  $c^2$  - 3 ) (
- 870377581802546524522262810187710657424  $c^6$ 
+ 7891339202462898562636842183835582800  $c^4 \sqrt{30}$ 
+ 675610326837999333653268745803921063516  $c^4$ 
+ 10025016159669674173039721517094214400  $c^2 \sqrt{30}$ 
+ 12431362440632888776769246015007796640  $c^2$ 
- 13770845075680070691004724800666234700  $\sqrt{30}$ 
+ 76933874542015283734919032298160072893 ) (18)
```

```
> # explizit loesbar, da nur gerade exponenten
```

```
> Digits:=20:
```

```
> los:=solve (evalf (weg) , c2) ;
```


$$\begin{aligned} \text{los} := & 0.8660254038, -0.8660254038, -0.9553704535, 0.9553704535, -0.008467518621 \\ & - 0.2085542404 I, 0.008467518621 + 0.2085542404 I, -0.008467518621 \\ & + 0.2085542404 I, 0.008467518621 - 0.2085542404 I \end{aligned} \quad (19)$$

$$> \text{c2} := \text{solve}(-3^{(1/2)} + 2 * \text{c2}, \text{c2});$$

$$\text{c2} := \frac{\sqrt{3}}{2} \quad (20)$$

$$> \text{evalf}(2 * \arccos(\text{c2}) * 180 / \text{Pi});$$

$$60. \quad (21)$$

$$> \text{factor}(\text{T});$$

$$\begin{aligned} -\frac{1}{2} & \left((-1 + 2 s2) \left(-777400000 s2^7 + 3151200 s2^5 \sqrt{30} - 388700000 s2^6 \right. \right. \\ & - 577824000 s2^4 \sqrt{30} + 24255634000 s2^5 + 424910520 s2^3 \sqrt{30} + 9916283000 s2^4 \\ & + 1446392640 s2^2 \sqrt{30} - 61049949694 s2^3 + 1452398400 s2 \sqrt{30} - 14927264693 s2^2 \\ & \left. \left. + 7103136000 \sqrt{30} + 111564949920 s2 - 2544099450 \right) \right) \end{aligned} \quad (22)$$

$$> \text{factor}(\text{hilf2});$$

$$\frac{(-1 + 2 s2) (2 s2 + 1)}{4} \quad (23)$$

$$> \text{s2} := \text{solve}(-1 + 2 * \text{s2}, \text{s2});$$

$$\text{s2} := \frac{1}{2} \quad (24)$$

$$> \text{factor}(\text{yes1});$$

$$\begin{aligned} \frac{1}{3235731} & \left(2 (35 \sqrt{30} - 1809) (521260 t3 \sqrt{30} + 3235731 t3^2 + 1980342 t3 \right. \\ & \left. - 3235731) (t3^2 - 2 t3 - 1) \right) \end{aligned} \quad (25)$$

$$> \text{factor}(\text{yes4});$$

$$\frac{26 (27 \sqrt{30} + 350) (7780 t3 \sqrt{30} + 10063 t3^2 - 95634 t3 - 10063) (t3^2 - 2 t3 - 1)}{10063} \quad (26)$$

$$> \text{t3} := \text{solve}(-t3 + 1 + 2^{(1/2)}, t3);$$

$$t3 := 1 + \sqrt{2} \quad (27)$$

$$> \text{evalf}(2 * \arctan(t3) * 180 / \text{Pi});$$

$$135. \quad (28)$$

$$> \text{factor}(\text{yes2});$$

$$\begin{aligned} -\frac{1}{4713065} & \left(4 (1131 \sqrt{2} \sqrt{15} + 1508 \sqrt{15} + 7400 \sqrt{2} + 11100) (7940186 c1 \sqrt{2} \sqrt{15} s1 \right. \\ & \left. - 3970093 \sqrt{2} \sqrt{15} + 9426130 c1^2 - 29921800 c1 s1 - 9426130 s1^2 + 14960900) \right) \end{aligned} \quad (29)$$

$$> \text{factor}(\text{yes3});$$

$$\begin{aligned} \frac{1}{26418119} & \left(8 (2880 \sqrt{2} \sqrt{15} + 3840 \sqrt{15} - 2218 \sqrt{2} - 3327) (7940186 c1 \sqrt{2} \sqrt{15} s1 \right. \\ & \left. - 3970093 \sqrt{2} \sqrt{15} - 26418119 c1^2 + 29921800 c1 s1 + 26418119 s1^2 - 14960900) \right) \end{aligned} \quad (30)$$

$$\begin{aligned} > \text{yo2} := & 7940186 * \text{c1} * \text{sqrt}(2) * \text{sqrt}(15) * \text{s1} - 3970093 * \text{sqrt}(2) * \text{sqrt}(15) + \\ & 9426130 * \text{c1}^2 - 29921800 * \text{c1} * \text{s1} - 9426130 * \text{s1}^2 + 14960900; \end{aligned}$$

$$\text{yo2} := 7940186 c1 \sqrt{2} \sqrt{15} s1 - 3970093 \sqrt{2} \sqrt{15} + 9426130 c1^2 - 29921800 c1 s1 \quad (31)$$

```

- 9426130 sI2 + 14960900
> yo3:=7940186*c1*sqrt(2)*sqrt(15)*s1 - 3970093*sqrt(2)*sqrt(15) -
26418119*c1^2 + 29921800*c1*s1 + 26418119*s1^2 - 14960900;
yo3 := 7940186 cI √2 √15 sI - 3970093 √2 √15 - 26418119 cI2 + 29921800 cI sI
+ 26418119 sI2 - 14960900 (32)
> hilf1:=c1^2+s1^2-1;
hilf1 := cI2 + sI2 - 1 (33)
> factor(resultant(yo2,hilf1,c1));
- 1
2180124301614001 (10 (-78552960844637
+ 11879232872740 √30) (4360248603228002 sI2 + 284610004090314 √30
- 1671693405153801) (2 sI2 - 1)) (34)
> factor(resultant(yo3,hilf1,c1));
- 1
2180124301614001 ((1394594693167631 + 118792328727400 √30) (
- 4360248603228002 sI2 + 284610004090314 √30 + 2688555198074201) (2 sI2 - 1)) (35)
> s1:=solve(2*s1-2^(1/2),s1);
sI := √2
2 (36)
> factor(yo2);
- (9426130 cI + 7940186 √15 - 10247835 √2) (-2 cI + √2)
2 (37)
> factor(yo3);
- (-2 cI + √2) (-52836238 cI + 15880372 √15 + 3503681 √2)
4 (38)
> c1:=solve(2*c1-2^(1/2),c1);
cI := √2
2 (39)
> #Probe
> #theta1=Pi/2,theta2=Pi/3,theta3=-Pi/2,
> simplify(arccos(c1)*180/Pi); #theta1/2
45 (40)
> simplify(arccos(c2)*180/Pi*2); #theta2/2
60 (41)
> simplify(arccos(c3)*180/Pi); #theta3/2
135 (42)

```

[Teil 2

```

> end4:=Qmult(Qkon(DQ4n[1]),Qmult(Qkon(DQ3n[1]),Qmult(Qkon(DQ2n[1]
),Qmult(Qkon(DQ1n[1]),Given[1]))));

```

$$\begin{aligned}
\text{end4} := & \left[\left[\frac{((7s4\sqrt{5} - 15c4)\sqrt{3} + 7\sqrt{5}c4 + 15s4)\sqrt{13}}{260} \right. \right. \\
& + \left. \left. \frac{(-13s4\sqrt{5} - 65c4)\sqrt{3}}{260} - \frac{\sqrt{5}c4}{20} + \frac{s4}{4} \right], \right. \\
& \left[\frac{((4\sqrt{3}s4 + 4c4)\sqrt{5} + 5\sqrt{3}c4 - 5s4)\sqrt{13}}{130} + \frac{\sqrt{5}(\sqrt{3}s4 + c4)}{10} \right], \\
& \left[\frac{((-s4\sqrt{5} + 15c4)\sqrt{3} - \sqrt{5}c4 - 15s4)\sqrt{13}}{260} + \frac{(13s4\sqrt{5} - 65c4)\sqrt{3}}{260} \right. \\
& + \left. \frac{\sqrt{5}c4}{20} + \frac{s4}{4} \right], \\
& \left. \left[\frac{((-2\sqrt{3}s4 - 2c4)\sqrt{5} - 5\sqrt{3}c4 + 5s4)\sqrt{13}}{130} + \frac{\sqrt{5}(\sqrt{3}s4 + c4)}{10} \right] \right]
\end{aligned} \tag{43}$$

> end56 := Qmult(DQ5n[1], DQ6n[1]);

$$\text{end56} := \begin{bmatrix} c5c6 - \frac{3s5s6\sqrt{13}}{13} \\ \frac{2c5s6\sqrt{13}}{13} \\ \frac{3c5s6\sqrt{13}}{13} + s5c6 \\ -\frac{2s5s6\sqrt{13}}{13} \end{bmatrix} \tag{44}$$

> factor(simplify(Norm(end4, 2, conjugate=false)^2));

$$c4^2 + s4^2 \tag{45}$$

> factor(simplify(Norm(end56, 2, conjugate=false)^2));

$$(c6^2 + s6^2)(c5^2 + s5^2) \tag{46}$$

> s4 := 2*t4 / (1+t4^2) : c4 := (1-t4^2) / (1+t4^2) :

> s5 := 2*t5 / (1+t5^2) : c5 := (1-t5^2) / (1+t5^2) :

> s6 := 2*t6 / (1+t6^2) : c6 := (1-t6^2) / (1+t6^2) :

> bed1 := factor(numer(simplify(end4[1] - end56[1]))) :

> bed2 := factor(numer(simplify(end4[2] - end56[2]))) :

> bed3 := factor(numer(simplify(end4[3] - end56[3]))) :

> bed4 := factor(numer(simplify(end4[4] - end56[4]))) :

> aha2 := factor(simplify(resultant(bed1, bed2, t4) / ((1+t5^2)^2 * (1+t6^2)^2))) ;

$$\text{aha2} := \frac{1}{3929} (5408000 (8\sqrt{13} + 69) (3929 + 3929 t5^4 t6^4 - 87360 t5^3 t6^3 + 87360 t5^3 t6) \tag{47}$$


```

> t5:=2^(1/2)-1;
                                     t5 :=  $\sqrt{2} - 1$  (58)
=
> factor(gcd(gcd(aha2,aha3),aha4));
                                     -1 - 2 t6 + t6^2 (59)
=
> solve(-1-2*t6+t6^2,t6);
                                      $\sqrt{2} + 1, 1 - \sqrt{2}$  (60)
=
> t6:=1-2^(1/2);
                                     t6 :=  $1 - \sqrt{2}$  (61)
=
> factor(gcd(gcd(bed1,bed2),gcd(bed3,bed4)));
                                     t4 - 2 -  $\sqrt{3}$  (62)
=
> t4:=solve(t4-2-3^(1/2),t4);
                                     t4 :=  $2 + \sqrt{3}$  (63)
=
> arctan(t4)*180/Pi*2;
                                     150 (64)
=
> arctan(t5)*180/Pi*2;
                                     45 (65)
=
> arctan(t6)*180/Pi*2;
                                     -45 (66)
=
> # somit erhalten wir genau die Drehwinkel, mit welchen die Pose
"Given" generiert wurde.

```